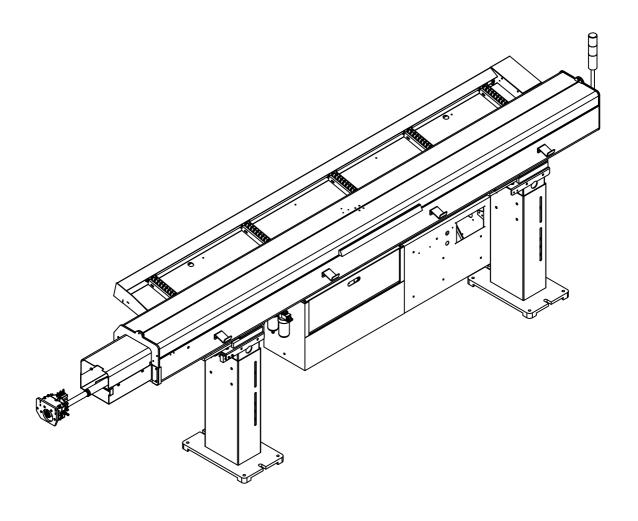
RANGER 112 Operation Manual



High loading speed Special development of design

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RANGER 112 HYDRODYNAMIC AUTOMATIC BAR FEEDER RANGER 112/25.25R EXT / RANGER 112/37.37R EXT

MANUAL FOR USE AND MAINTENANCE VER: 03 DATA: 2018/07/17 COD: BRG102032 S/H

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10 PARTS LIST

1. GENERAL INFORMATION



Please read the Manual carefully before operating bar feeder.

1.1 Contents of the manual

The feeder manufacturer provides this manual, which is an essential part of the integrated products. Please act according to the indication of the manual in order to assure operators' safety as well as the machines', and greatly achieve economic efficiency and to get the best output of the machine's capability. The important part is printed in boldface, and included the following marks:



HAZARD-WARNING:

Hazard! It is possible to hurt you seriously, please be careful.



CAUTION:

For preventing the accident or the loss of property, you should take precautions.



INFORMATION:

Special important know-how information

Please take use of the table of contents, you will quickly find the information you need.

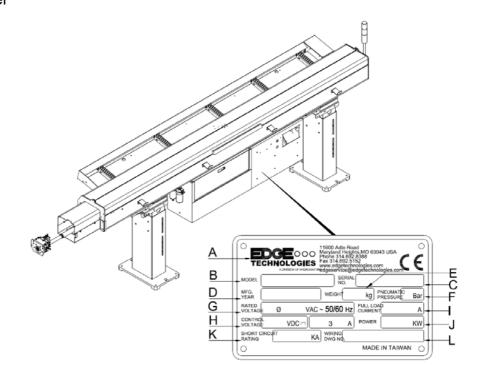


SKILLED:

The mark shown in the manual means that the machine should be operated by a qualified and expert operator. As to the other operation shall be handled by a qualified personnel or professional operator of bar feeder.

1.2 Machine data plate

- A. Name of manufacturer
- B. Model(Type)
- C. Serial Number
- D. Manufacture Date
- E. Weight of Machine
- F. Pneumatic Pressure
- G. Rated Voltage
- H. Control Voltage
- I. Full Load Current
- J. Power
- K. Short Circuit Rating
- L. Wiring Drawing Number





INFORMATION:

When inquiring or ordering the parts, please notify the manufacturer the above—mentioned in each standards.

1.3 Technical support

If you need any technical support, you can inquire the service center in the appendix at anytime.



INFORMATION:

When you need the support of technique, please refer to the label on the bar feeder. Tell us the data of the bar feeder.

2. TECHNICAL DATA

2.1 Instruction

The hydrodynamic automatic bar feeder is designed for full automatic lathe to auto feed material, the bar feeder is suitable for digital control sliding headstock lathe and fixed headstock lathe.

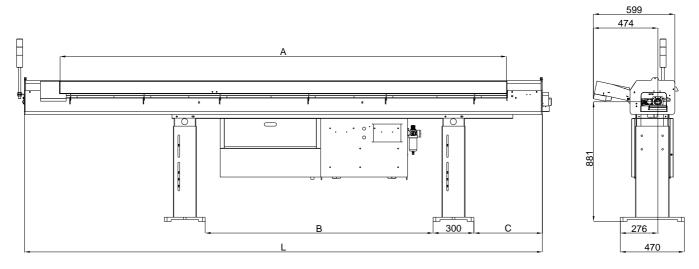
The program of the PLC system can control the bar feeder running with the lathe. The remote control box is easy to be operated.

The bar feeder can feed round bar, tubes and any other section of material. While the lathe is running, the guide channel is closed completely, at the same time; lubricating oil into the guide channel so that the noise and vibration can be reduced while the material is rotating in high speed. Furthermore, lubricating oil also can reduce the temperature resulted from friction so that the surface of the material can't be damaged.

The remnant material will be pushed out of the guide channel by the push bar or the next material.

The descriptions and legends of the manual are according to the operator stands at the left side of the lathe to be edited.

2.2 Machine footprint



MOD	27	37
L	3278 mm	4600 mm
A (Max. Bar Length)	2700 mm	3785 mm
В	1595 mm	2150 mm
С	584 mm	585 mm
Weight	385 kg	415 kg

2.3 Machine specifications

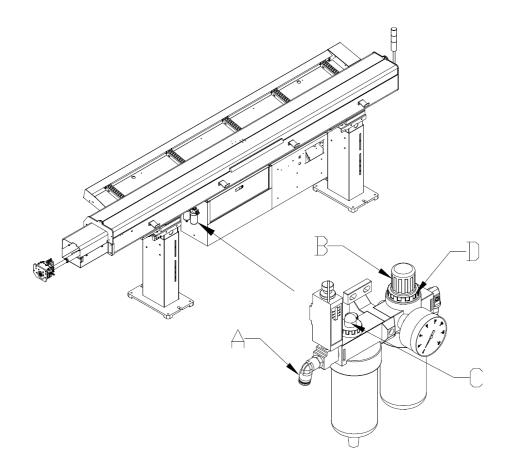
Bar Diameter	\bigcirc 1.5 mm (1/16") \sim 12 mm (1/2")
Dai Diametei	\bigcirc 2 mm (5/64") \sim 11 mm (7/16")
Channel Size	08 / 11 / 14
Bar Loading Capacity	220mm ~22 bar Ø10
Lubricant Specification	40 (L) ISO CKB 100
Power Supply	220 / 380V 0.4A 50 / 60Hz
Pneumatic Supply	5 - 7 kg/cm ²

2.4 Compressed air supply

2.4.1 Tube size for compressed air supply unit must be not less than 8 mm. The pressure should be within 7 kg / cm² and the consumption near 50L/H.

- **2.4.2** Put the air supply tube into (A). Then pull and turn around the knob (B) to set the pressure at 6 kg / cm².
- **2.4.3** Control air lubrication from cylinder , adjust (C) , 1-2 drops / 1000 L air if necessary.
- **2.4.4** Lubricating (D) , viscosity 32 Cat , temperature 40°C , ISO VG type.

Adaptive lubricant				
BP ENERGOL HLP32	AGIP OSO 32	MOBIL DTE 24	ESSO NUTO H32	



2.5 Guide channel - Selection

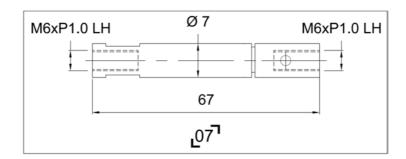
	Diameter of her	Diameter of bar (mm)			
Diameter of guide	Diameter of bar pusher (mm)		Max.		
channel (mm)		Min.			
8	7	1.5	5.5	7	
11	10	2	8	10	
14	12	3	10	12	

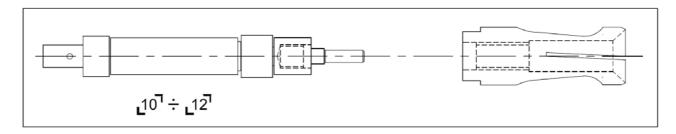


CAUTION

Note!! Outer diameter of the collet must be smaller 0.5 mm than diameter of bar pusher at least.

2.6 Revolving tip - Selection



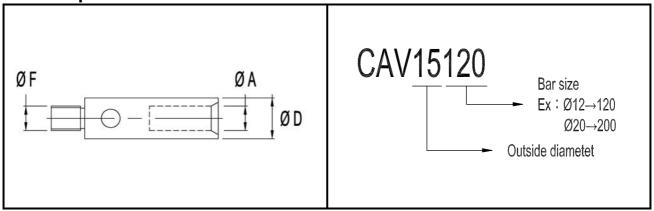


MOD	Ø A	Part No. of revolving tip		
MOD.	Ø A	Left thread	Right thread	
7 Ø 7		CAV07000		
10 Ø 10			IER0610001	
12	Ø 12.5		IER0712000	

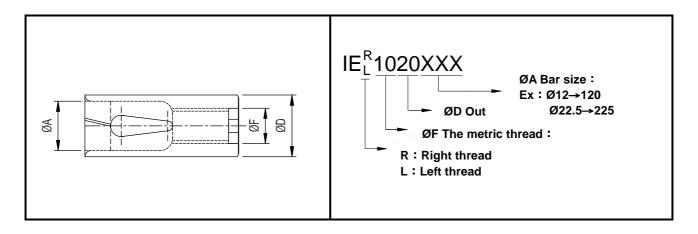
2. TECHNICAL DATA

2.7 Collet - Selection

2.7.1 Specification of the collet for round bar



ØF ØA		M10 xP1.0 LH
mm	in	Ø7 Ø D
2		CAV07020
2.4	3/32"	CAV07024
2.5		CAV07025
3		CAV07030
3.5		CAV07035
4	5/32"	CAV07040
4.4	11/64"	CAV07044
4.5		CAV07045
4.6		CAV07046
4.8	3/16"	CAV07048
5		CAV07050
5.2	13/64"	CAV07052
5.5	_	CAV07055



ØF		M6 x0.75	M7 x0.75
₩ Mm	in	Ø10	Ø12
2	5/64"	0610020	0712020
2.5		0610025	0712025
2.8	7/64"	0610028	0712028
3		0610030	0712030
3.2	1/8"	0610032	0712032
3.5		0610035	0712035
3.6	9/64"	0610036	0712036
4	5/32"	0610040	0712040
4.4	11/64"	0610044	0712044
4.5		0610045	0712045
4.8	3/16"	0610048	0712048
5		0610050	0712050
5.2	13/64"	0610052	0712052
5.5	7/32"	0610055	0712055
6	15/64"	0610060	0712060
6.3	1/4"	0610063	0712063
6.5		0610065	0712065
7		0610070	0712070
7.2	9/32"	0310072	0712072
7.5	19/64"	0610075	0712075
8	5/16"	0610080	0712080
8.4	21/64"		0712084
8.5	11/32"		0712085
9	23/64"		0712090
9.5	3/8"		0712095
10	25/64"		0712100

2.7.2 Specification of the collet for polygonal material

b b	a	Ø PINZA COLLET ZANCE PINCE	a	- b	Ø PINZA COLLET ZANCE PINCE
3	3.48	3.25	1	1.41	1.3
3.5	4.04	3.8	1.5	2.12	2
4	4.61	4.5	2	2.82	2.7
4.5	5.19	5	2.5	3.53	3.4
5	5.77	5.5	3	4.24	4
5.5	6.35	6.2	4	5.65	5.5
6	6.92	6.8	4.5	6.36	6.2
6.5	7.50	7.3	5	7.07	6.8
7	8.08	7.8	5.5	7.77	7.5
7.5	8.66	8.5	6	8.48	8.3
8	9.23	9	6.5	9.19	9
9	10.39	10.2	7	9.89	9.7
10	11.54	11.3	8	11.31	11
11	12.70	12.5	8.5	12.01	11.8

	Ø	PINZA COLLET ZANCE PINCE		PINZA COLLET ZANCE PINCE
INCH	mm	inch	INCH	
1/8	3.5	9/64	1/8	3.25
3/16	5.25	13/64	3/16	4.75
1/4	7	9/32	1/4	6.5
5/16	8.75	11/32	5/16	8
3/8	10/75	27/64	3/8	9.5
7/16	12.5	31/64	7/16	11

3. TRANSPORTATION RANGER 112

3. TRANSPORTATION



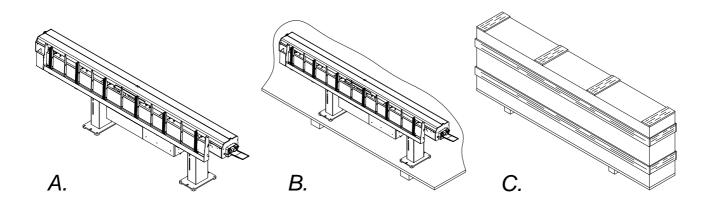
HAZARD-WARNING

The lifting and handling are to be operate with proper equipment (Refer to the weight of chapter 3.2) and by skilled staff, trained for the kind of transportation.

3.1 Packaging

The bar feeder will be arrived in one of three ways:

- A. Without packaging.
- **B.** On the pallet, Put the feeder on the pallet and package the feeder with plastic film.
- C. Created in a wooden box, and package the feeder with plastic film.



3.2 Transportation



Verify the equipment to be used for moving the bar feeder is rate to safety lift the weight of the bar feeder plus the packaging material.

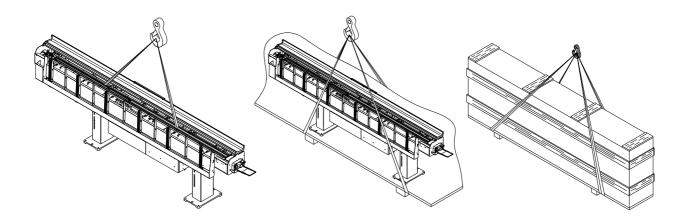


CAUTION

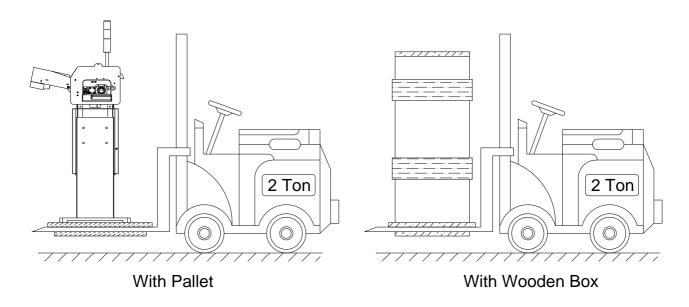
Lifting the bar feeder under the magazine with a lift truck or slings may cause damage to the machine.

3.2.1 Lifting by straps or slings

Hazard! It is possible to hurt you seriously, please be careful.



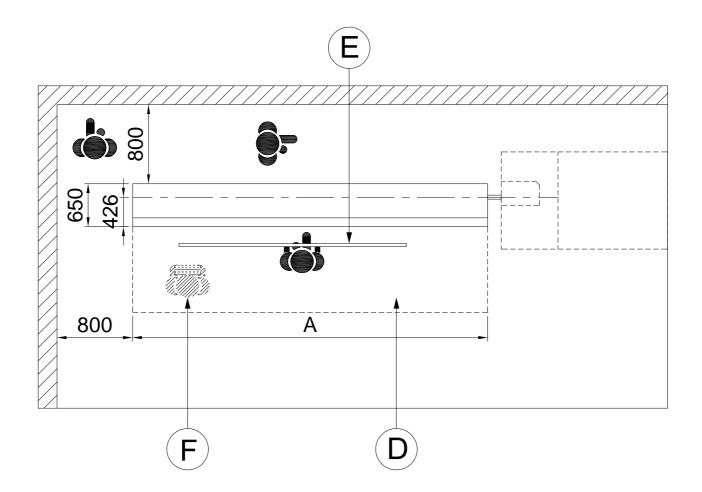
3.2.2 Lifting by lift truck



3.3 Installation area



The bar feeder must be bolted to a sound, reasonably level floor using anchor bolts. The area surrounding the machine must provide sufficient clearance the operator access to both sides and the near of machine as shown in the diagram below. Other necessaries are suitable lighting and compressor air supply. The bar feeder is not suitable for and can be adapted to use in an explosive surrounding. Area: (D-Operator area), (E-Material supply area), (F-Remain removal area)



List 1. - Size of appearance

Туре	Size	A (mm)
RANGER 112	27	3278 mm
	37	4600 mm

4. INSTALLATION

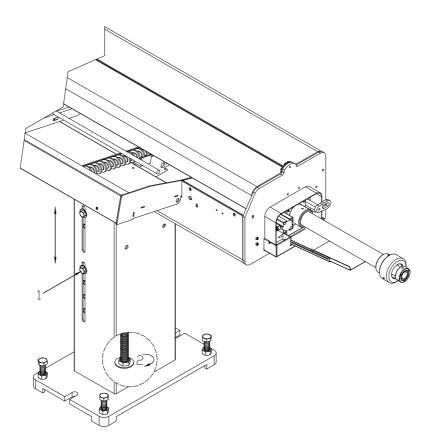
4.1 Bar feeder - Installation



Prior to beginning the bar feeder installation the lathe must be properly leveled. It is strongly recommended that the lathe be anchored to the floor to prevent it from shifting.

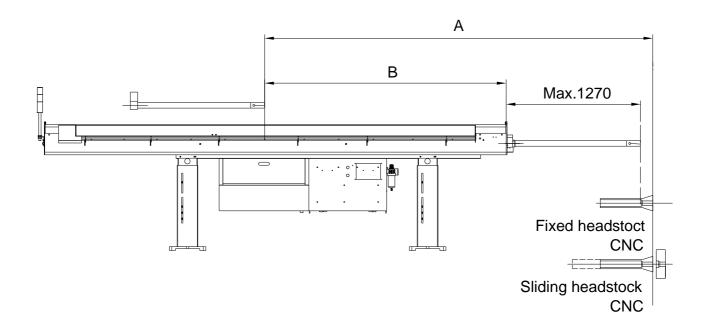
4.2 Height adjustment

- **4.2.1** Disengage the screw (1).
- **4.2.2** Adjust the screw (2) and shift from up to down. Adjust the height to a straight line between the center of the bar feeder and the center of the lathe.



4.3 Initial position

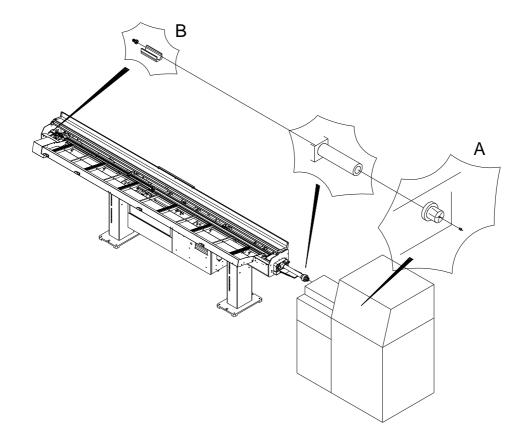
The bar feeder should set the proper distance from the lathe. The distance is as below:



Model	Α	В
27	2700 mm	1720 mm
37	3785 mm	2750 mm

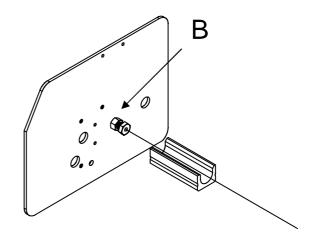
4.4 Adjustment of center

The bar feeder is aligned to the lathe spindle by use of a nylon string which is stretched between the lathe collet/chuck and alignment fitting at the rear plate of the bar feeder. This string indicates the centerline of two machines. Please prepare a nylon string (1mm) and pull it from the lathe (A) to the end of the bar feeder (B).



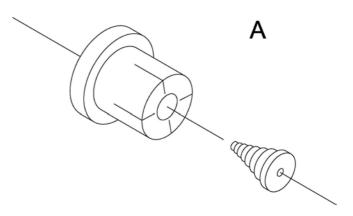
4.4.1 For rear plate of feeder

Secure nylon thread on to the axis screws (B point) of bar feeder, and then pull the thread through spindle hole.



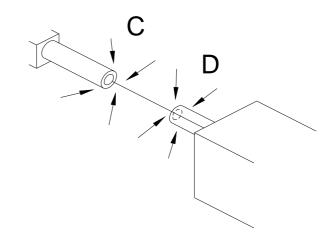
4.4.2 For collet/chuck of lathe

Insert the center tool into the lathe collect/chuck, then pull the nylon string to be straight.



4.4.3 Aligning the center line

The bar feeder is aligned by moving the front and rear stands so that the distance from the string to the centerline of the lathe spindle and the centerline of opening of the anti-vibration device is equal on all sides to within 0.15mm.



4.5 Securing and fastening of the bar feeder

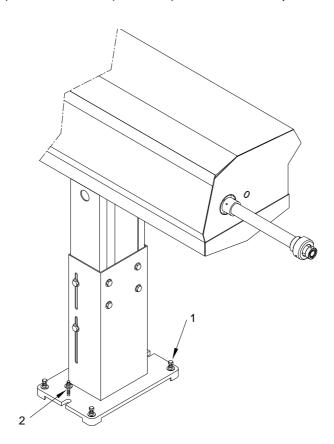


CAUTION

Failure or bad to fix the bar feeder to the floor can be the main cause of bar feeder bad operation and resulting damaging.

Place steel anchor plates and spacer under the four outside corner of the bar feeder. Thread the 4 screws (1) fully and fixing the nuts.

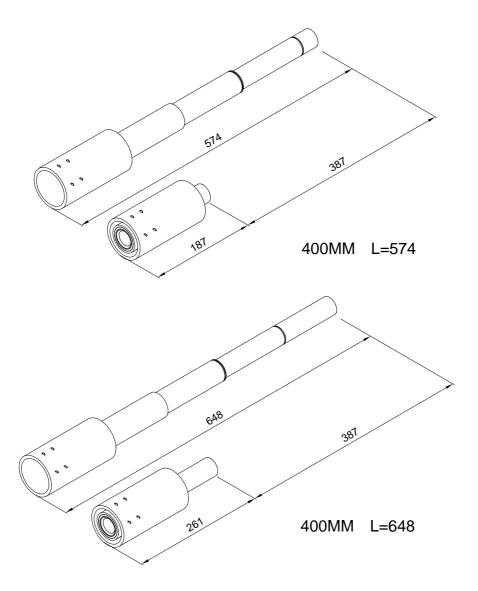
Drill the floor (2) with Ø16mm (5/8 inch) and fix with expansion plugs.



4.6 Installation accessories

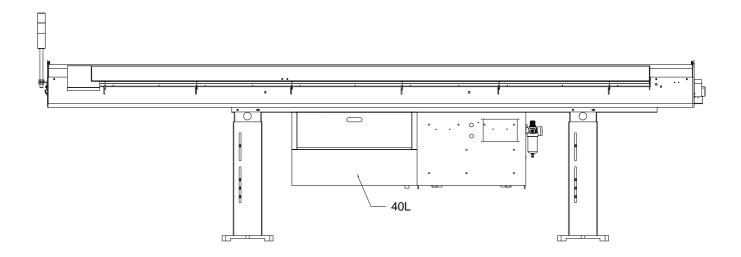
4.6.1 Moveable anti-vibration device (OPTION): The anti-vibration device is fixed at the end of the spindle of the lathe, using a bar to adjust the center of the anti-vibration.

- **4.6.2 Synchronization connecting rod:** Fix the connecting rod at the movable anti-vibration and makes it move smoothly.
- **4.6.3** Fixed front nose: Fix it at the support of nose which is in front of the bar feeder.
- **4.6.4 Telescopic front nose:** End of the telescopic front nose fix at the front of the telescopic front nose connects with the plate of the lathe.
- **4.6.5** Oil ring: Fix the oil ring in front of the fixed front nose or telescopic front nose.



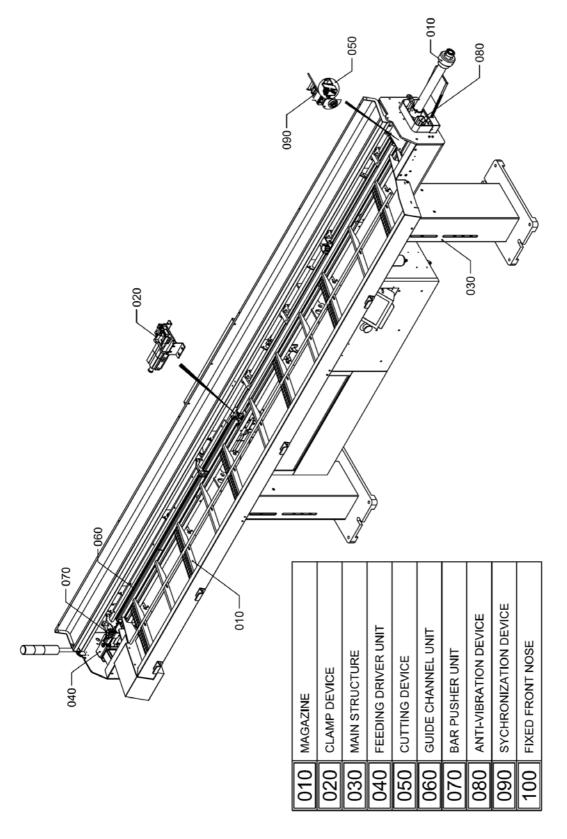
4.7 Guide channel lubricate

ISO and UNI brand	Brand	Description
	Agip	Acer 100
	Api	Api Cis 100
	ВР	Energol CS 100
	Castrol	Magna 100
	Chevron	Circulating Oil 100
	Elf	Movixa 100
	Esso	Nuto 100
	Fina	Solna 100
CKB 100	IP	IP Hermea 100
	Kluber	Crucolan 100
	Mobil	Vectra Oil Heavy
	Olio FIAT	Daphne LPN 100
	Roloil	Arm V 100
	Shell	Vitrea 100
		Tell us C 100
	Tam oil	Tell us C 100
	Texaco	Industrial Oil 100
	Total	Cortis 100
	Q8	Azolla ZS 100



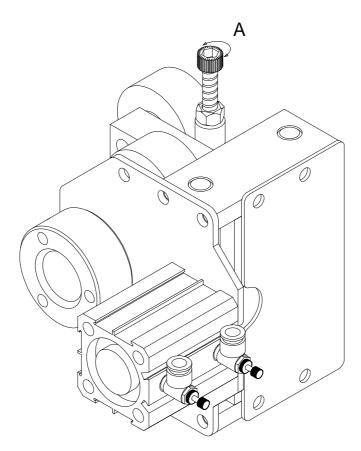
5. ADJUSTMENT AND SETTING

5.1 Structure of the bar feeder



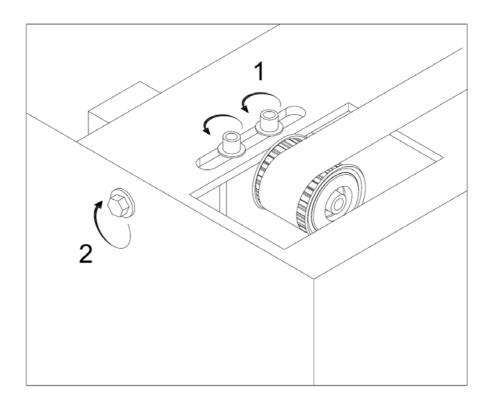
5.2 Adjust and fix the anti-vibration device

- **5.2.1** Load a bar using the bar feeder into the lathe and close lathe collet.
- **5.2.2** Press the Pre-Auto button , both Anti-vibration devices will close.
- **5.2.3** Back screw (A) off counterclockwise until no tension is felt on the screw
- **5.2.4** Press the Manual button , then the Pre-Auto Button rollers are closed onto bar.
- **5.2.5** Rotate screw (A) clockwise until tension is felt, continue to rotate screw clockwise for ¼ turn.
- **5.2.6** Tighten jam nut.
- **5.2.7** Press the manual button



5.3 Pusher belt

- **5.3.1** Loosen locking screw (1) for the tensioner.
- **5.3.2** Rotate knob (2) clockwise to tighten the belt for suitable tension.
- **5.3.3** Tighten the locking screw (1).



6. OPERATIONS AND DESCRIPTION

6.1 Par storage distinction and preparation



CAUTION

Please don't put the material out of standard.

The max length of material

Туре	Mod	Max length mm (ft)
RANGER 112	27	3278
	37	4600

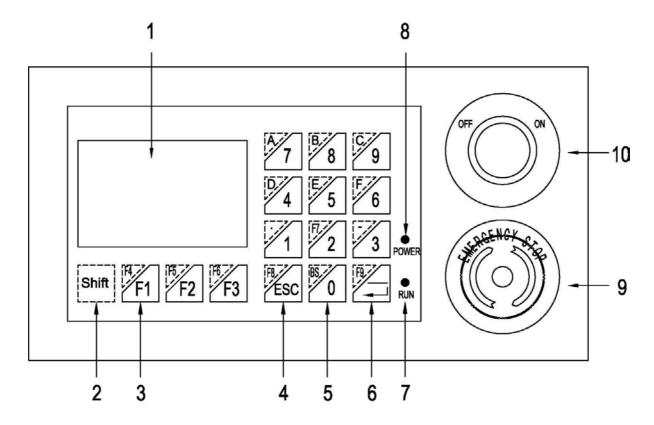


INFORMATION

The flatness of material must be within 0.5mm/M.

6.2 Operation description

6.2.1 H/M function description



NO.	Function	
1	LCD Display area	
2	Shift	
3	Function	
4	ESC	
5	Number	
6	Enter	
7	Run light	
8	Power light	
9	Emergency STOP	
10	Start	

6.2.1.1 H/M Program selection:

Press the key according to the indication on the display.

- (1) F1A:Page up
- (2) F2 :Page down
- (3) F3 :Back to the main menu

6.2.1.2 Value of parameter selection:

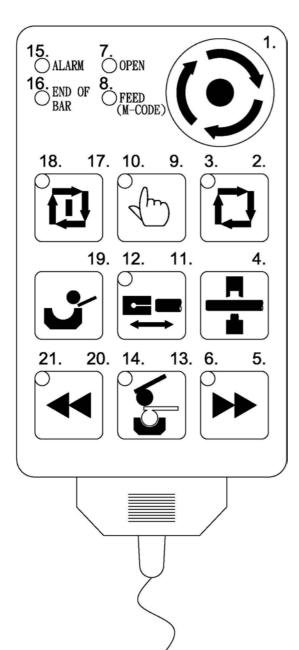
- (1) Input numbers as your request from 0 ~ 9.
- again, the input is finished. If you want to give up the input that you set, press FB to give up.

6.2.1.3 F1~F9 Function description:

- (1) Select F1 \sim F3, please press these three keys directly.
- (2) Select F4 ~ F9, please press and hold Shift key, and then select other keys as you want.

6.2.2 Description of remote control pendant

6.2.2.1 Description of button and indication light



NO.	Code	Function
1.	ES2	Emergency STOP
2.	DS6	Automatic mode
3.	LDS6	Automatic mode light
4.	DS10	Manual clamping
5.	DS1	Manual advance (Right)
J.		Manual retreat (Left)
6.	LDS1	Origin point light (Left)
7.	L3	Chuck open light
8.	L4	Allow feeding on
9.	DS7	Manual mode
10.	LDS7	Manual mode light
11.	DS3	Manual clamping in/out
12.	LDS3	Clamping in light
13.	DS4	Manual bar-pusher rise/down
14.	LDS4	Bar pusher down light
15.	L2	Alarm light
16.	L1	Bar end
17.	DS5	Automatic start
18.	LDS5	Automatic start light
19.	DS9	Manual loading
20	DS2	Manual advance (Right)
20.		Manual retreat (Left)
21.	LDS2	+Z light (Left)

6.2.2.2 Operation description

(1) Advance / retreat at low-speed

(When the lathe on the left, the motion of and are opposite).

Advance at low-speed, press and .

Retreat at low-speed, press and .

(2) Automatic work operation (self-motion)

While and the guiding light to twinkle, press and start to work automatically. Or while and guiding light off, and either or is on, press and start to work automatically.

(3) Resetting the Bar Feeder Home Position

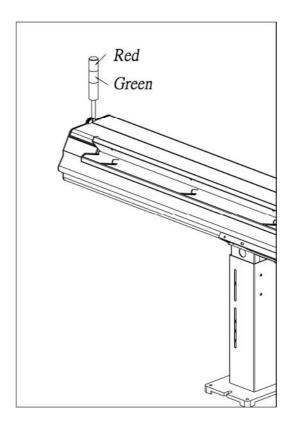
When guide channel up/down light on, press and simultaneously for 3 seconds to begin resetting the bar feeder home position.

6.2.3 Indicator Light

When Red light is on, bar feeder is in emergency stop.

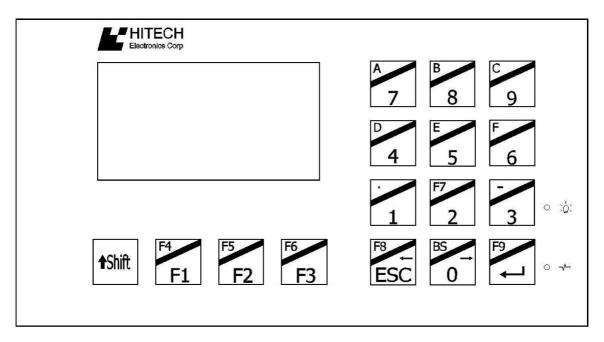
When Green light is on, bar feeder is i machining mode.

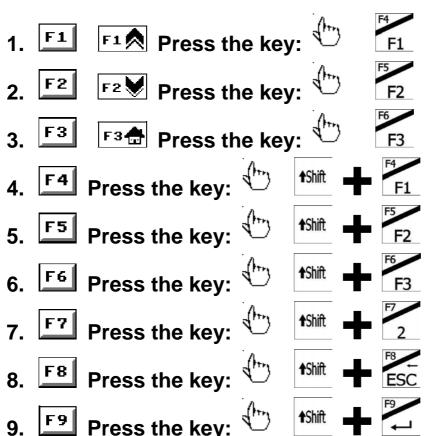
When Green light is flashing, bar feeder is in bar change operation.



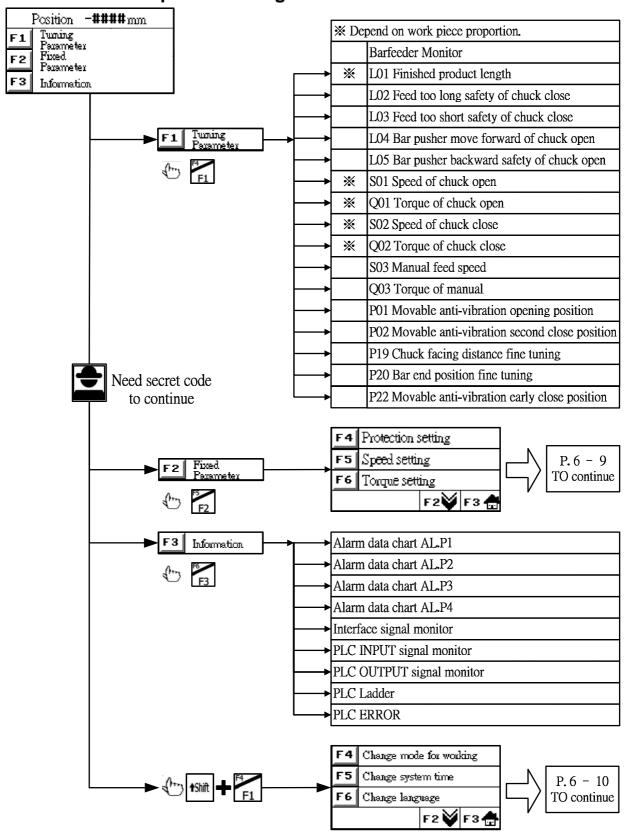
6.3 Description of settings and parameter

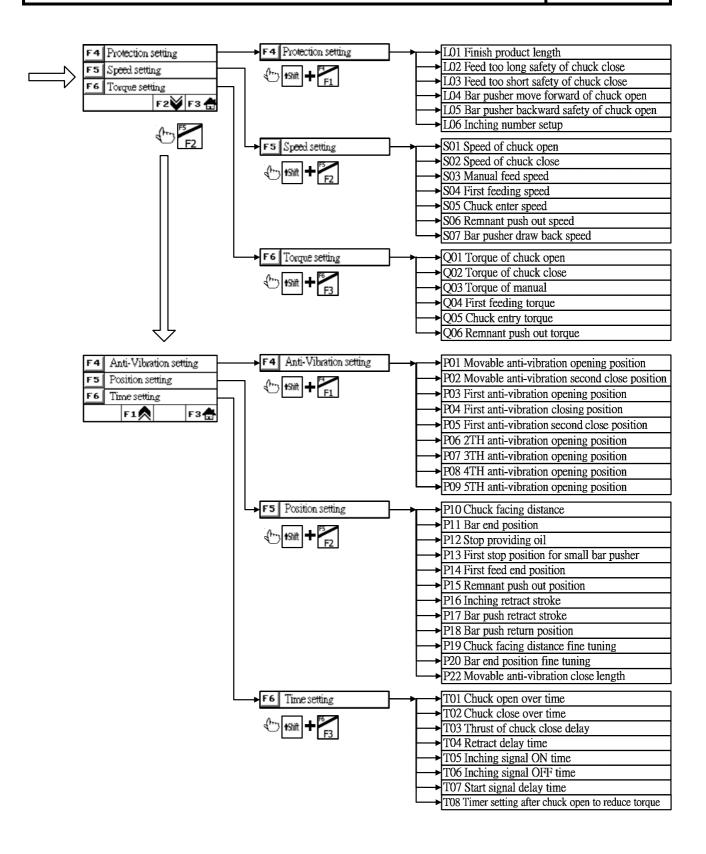
6.3.1 HMI Program selection

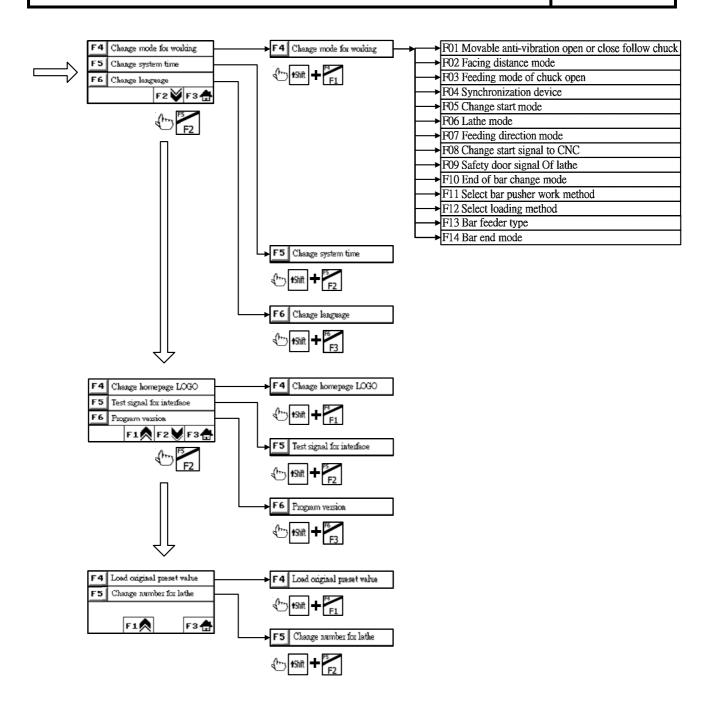




6.3.2 Parameter picture driftage







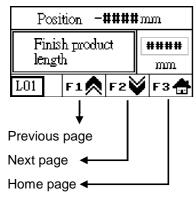
6.3.3 Description of settings and parameter

F1 Turning parameter [User parameter]			
Parameter NO	Parameter name	Parameter description	
	Barfeeder Monitor		
L01	Finished product length	Use the Bar end position to generate a signal for bar end.	
L02	Feed too long safety of chuck close	Prevents bars from feeding over the length of finished product. To disable parameter function, please set the value to zero.	
L03	Feed too short safety of chuck close	Prevents bars from feeding length less than finished product. To disable parameter function, please set the value to zero.	
L04	Bar pusher move forward of chuck open	Under automatic mode, the bar pusher move forward and the distance is large than the setting value during chuck opened.	
L05	Bar pusher backward safety of chuck open	Under automatic mode, when the bar pusher move backward and the distance is large than the setting value during chuck opened.	
S01	Speed of chuck open	The speed of the bar pusher move forward under automatic mode and the chuck is opened.	
Q01	Torque of chuck open	The torque of the bar pusher move forward when the chuck is opened under automatic mode.	
S02	Speed of chuck close	The speed of the bar pusher move forward under automatic mode and the lathe chuck is closed.	
Q02	Torque of chuck close	The torque of the bar pusher moves forward when the chuck is closed under automatic mode.	
S03	Manual feed speed	The motor turning speed when the bar pusher move forward under manual mode.	
Q03	Torque of manual	The motor torque of the bar pusher moves forward or backward under manual mode.	
P01	Movable anti-vibration opening position	The position of the movable anti-vibration device opened under automatic operation.	
P02	Movable anti-vibration second close position	The Second close position of movable anti-vibration device stands for the position of bar pusher is over the value of parameter, P01 ; the anti-vibration can operate the second close function to clamp bar pusher.	
P19	Chuck facing distance fine tuning	Fine tuning for chuck facing position as the datum of chuck facing distance P10 . If the adjustment quantity is less than 200 or large than 200, please adjust the value of chuck facing distance P10 .	
P20	Bar end position fine tuning	Fine tuning for the bar end position. If the fine tuning quantity is less than 200 or large than 200, then adjust the parameter P11 , bar end position value.	
P22	Movable anti-vibration early close position	Under Auto-Mode, Anti-vibration Device will close when bar pusher reached this parameter setup position.	

6.3.4 Parameter application

6.3.4.1 Fixed parameter / enter password "258"

3.7XL Generally value:



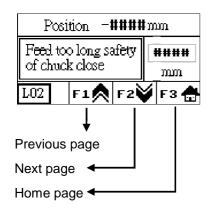
Parameter description: The finished product length will be the workpiece length adding the cutter thickness. This parameter setting may affect the bar end setting.

Setting method: Input the required length.

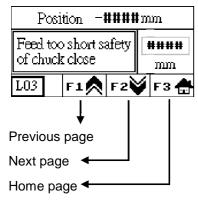
For example: Workpiece 47mm + thickness of cutter 3mm = The finished product length 50mm. So we will set finished product Length to be 50mm.

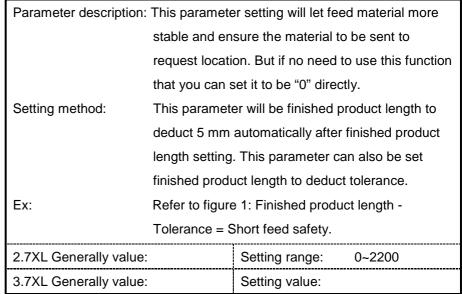
2.7XL Generally value: Setting range: 0~2000

Setting value:

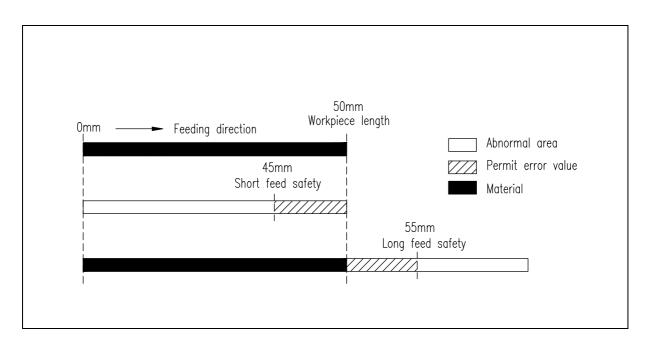


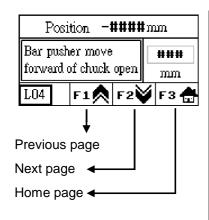
Parameter description: This parameter setting will let feed material more stable and ensure the material to be sent to request location. But if no need to use this function that you can set it to be "0" directly. Setting method: This parameter will be finished product length to add 5 mm automatically after finished product length setting. This parameter can also be set finished product length to add tolerance. Ex: Refer to figure 1: Finished product length + Tolerance = Long feed safety. 2.7XL Generally value: Setting range: 0~2200 3.7XL Generally value: Setting value:





(Figure 1)





Parameter description: In automatic mode to set the pusher safety distance

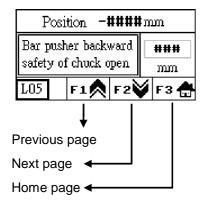
during chuck open. If pusher exceeds distance longer than this safety distance that the bar feeder

will alarm.

Setting method: Input the required length.

Note: The parameter is disabled if set to zero.

2.7XL Generally value:	Setting range:	0~550
3.7XL Generally value:	Setting value:	



Parameter description: In automatic mode to set the pusher safety distance

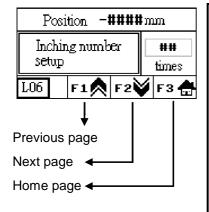
during chuck open. If pusher retreat distance is longer than this safety distance that the bar feeder

will alarm.

Setting method: Input the required length.

Note: The parameter is disabled if set to zero.

2.7XL Generally value:	Setting range: 0~500
3.7XL Generally value:	Setting value:



Parameter description: During changing the new bar and the bar pusher

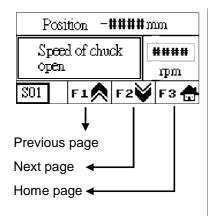
stocks or cannot push the new bar toward to the chuck facing position, bar pusher will start the inching movement and the frequency according to this setting value. If the new bar fails to reach chuck facing position and inching frequency exceeds the setting value then bar feeder will show

Alarm16.

Setting method: Input the number of required inching movement

times.

2.7XL Generally value:	Setting range:	0~50
3.7XL Generally value:	Setting value:	



Parameter description: The speed of the pusher during in automatic mode

when lathe chuck open.

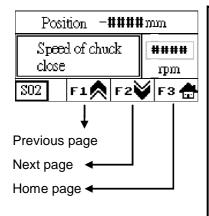
Setting method: According to the bar material size and torque of

chuck close to adjust speed.

Note: When setting value is too high it could cause servo

failure.

2.7XL Generally value:	Setting range:	0~500
3.7XL Generally value:	Setting value:	



Parameter description: The speed of the pusher during in automatic mode

when lathe chuck close.

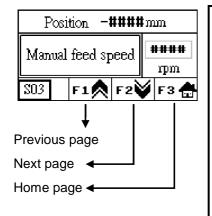
Setting method: According to the bar material size and torque of

chuck open to adjust speed.

Note: When setting value is too high it could cause servo

failure.

2.7XL Generally value:	Setting range:	0~500
3.7XL Generally value:	Setting value:	

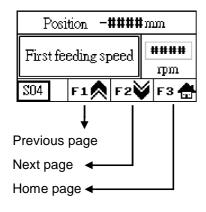


Parameter description: The pusher speed of manual operation.

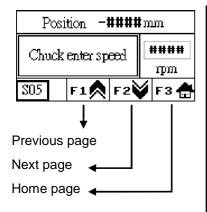
Setting method: According to the required speed and manual

operation torque to adjust speed.

2.7XL Generally value:	Setting range:	0~500
3.7XL Generally value:	Setting value:	



Parameter description: The first bar material feeding means guide channel open and bar pusher raising up. The first bar material feeding speed is the pre-feeding pusher speed as the pusher rising up. Setting method: Input the required speed to be the first bar material feeding speed parameter. Note: If the speed of pusher is too fast that bar material will pass clamping device to let clamping device miss bar material. 2.7XL Generally value: Setting range: 0~500 3.7XL Generally value: Setting value:

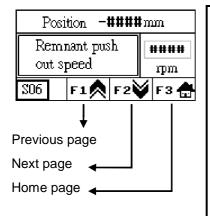


Parameter description: The speed of pusher entering chuck means that the speed of pusher pushes the new bar material to lathe chuck facing position.

Setting method: According to required speed and torque of entering chuck to adjust speed.

Note: Set actual speed to avoid crashing.

2.7XL Generally value:	Setting range:	0~500
3.7XL Generally value:	Setting value:	



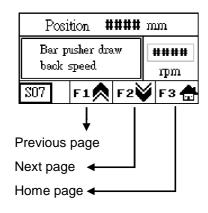
Parameter description: The speed of the bar pusher pushes out remnant

when receiving bar end signal.

Setting method: Input the required speed.

Note: Set actual speed to avoid crashing.

2.7XL Generally value:	Setting range:	0~500
3.7XL Generally value:	Setting value:	

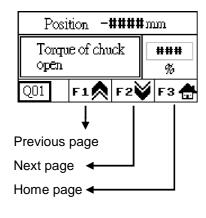


Parameter description: Retracting speed of the bar pusher in manual or

automatic mode.

Setting method: Input the required speed.

2.7XL Generally value:	Setting range: 0~1000
3.7XL Generally value:	Setting value:



Parameter description: The torque of pusher moves forward when

automatic mode and lathe chuck open.

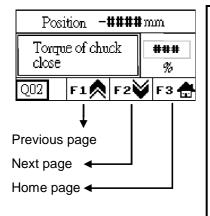
Setting method: According to the bar material size and speed of

chuck open to adjust torque.

Note: When setting value is too high it could cause servo

failure.

2.7XL Generally value:	Setting range:	0~800
3.7XL Generally value:	Setting value:	



Parameter description: The torque of pusher moves forward when

automatic mode and lathe chuck close.

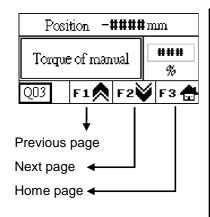
Setting method: According to the bar material size and speed of

lathe chuck close to adjust torque.

Note: When setting value is too high it could cause servo

failure.

2.7XL Generally value:	Setting range:	0~800
3.7XL Generally value:	Setting value:	



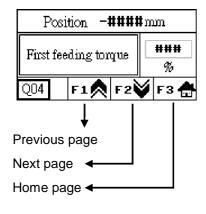
Parameter description: The torque of bar pusher moves forward in manual

operation mode.

Setting method: According to required torque and speed of manual

operation mode to adjust torque.

2.7XL Generally value:	Setting range: 0~800
3.7XL Generally value:	Setting value:



Parameter description: The torque of pusher entering chuck means the

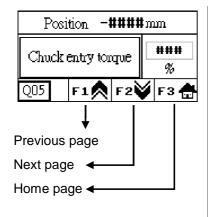
torque of pusher when pushing the new material to

chuck facing.

Setting method: According to required torque and speed of manual

mode to adjust torque.

2.7XL Generally value:	Setting range:	0~800
3.7XL Generally value:	Setting value:	



Parameter description: The torque of pusher entering chuck means torque

of pusher when loading new bar material and

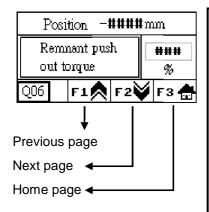
pushing to facing position.

Setting method: According to required torque and speed of entering

chuck to adjust torque.

Note: The setting value is too large will cause crashing.

2.7XL Generally value:	Setting range:	0~800
3.7XL Generally value:	Setting value:	



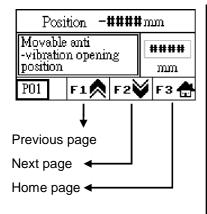
Parameter description: The torque of the bar pusher pushes out remnant

when receiving bar end signal.

Setting method: Input the required torque.

Note: The setting value is too large will cause crashing.

2.7XL Generally value:	Setting range:	0~800
3.7XL Generally value:	Setting value:	



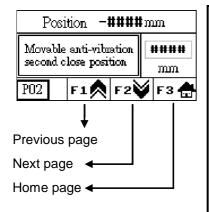
Parameter description: In automatic mode anti-vibration device open position.

Setting method: There are two open positions as following.

 Let lathe spindle move to Z limit position and pusher move forward nearby anti-vibration .Then input the current position.

 Let lathe spindle move to spindle retreating position when working mode and lathe chuck open. Then move pusher forward nearby anti-vibration. Then input the current position.

2.7XL Generally value: Setting range: 0~5000
3.7XL Generally value: Setting value:



Parameter description: Move anti-vibration device will do the second close

action to clamp bar pusher when bar pusher

passed anti-vibration open position.

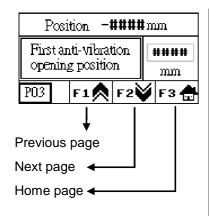
Setting method: This position will be movable anti-vibration open

position to add 150 mm.

Note: To disable this parameter function, set the value to

zero.

2.7XL Generally value:	Setting range: 0~5000
3.7XL Generally value:	Setting value:



Parameter description: In automatic mode setting 1st Anti-Vibration Device

open position.

Setting method: In manual mode collet will be pushed forward until

30~50mm before 1st anti vibration device. Then

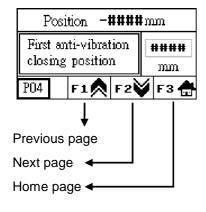
input the current position.

Note: First anti–vibration should be opened before the

collet will be arrived to avoid the material was

separated from the collet.

2.7XL Generally value:	Setting range:	0~5000
3.7XL Generally value:	Setting value:	



Parameter description: In automatic mode the pre-feeding pusher will push

bar material when the pusher rising. Then anti

vibration device will open when pusher pushes bar

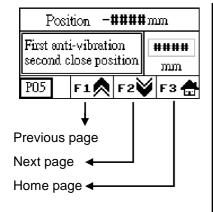
material to touch chuck facing sensor.

Setting method: Input the required length.

Note: To disable this parameter function, set the value to

zero.

2.7XL Generally value:	Setting range:	0~5000
3.7XL Generally value:	Setting value:	



Parameter description: Under Auto-Mode, this parameter is to setup how

much distance to go before the clamp of

Anti-vibration Device closes again, after passing

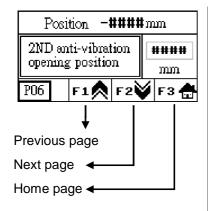
"First anti-vibration opening position."

Setting method: Input the required length.

Note: To disable this parameter function, set the value to

zero.

2.7XL Generally value:	Setting range: 0~5000
3.7XL Generally value:	Setting value:



Parameter description: 2nd Anti-Vibration Device open position in working mode.

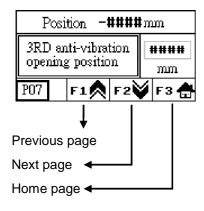
Setting method: In manual mode pusher will be pushed forward until 30~50mm before 2nd anti vibration device.

Then input the current position.

Note: The Second anti–vibration should be opened

before the end of the push bar will be arrived to avoid the material was separated from the collet.

2.7XL Generally value:	Setting range: 0~5000
3.7XL Generally value:	Setting value:



Parameter description: 3rd Anti-Vibration Device open position in working

mode.

Setting method: In manual mode pusher should be pushed

30~50mm before 3rd anti vibration device. Then

input the current position.

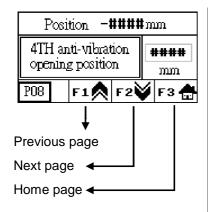
Note: The Third anti–vibration should be opened before

the end of the push bar will be arrived to avoid the

material was separated from the collet.

2.7XL Generally value: Setting range: 0~5000

3.7XL Generally value: Setting value:



Parameter description: 4th Anti-Vibration Device open position in working mode.

Setting method: In manual mode pusher will be pushed forward

west 20. Forms he fore 4th anti-vibration device

until 30~50mm before 4th anti vibration device.

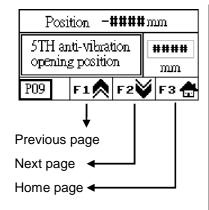
Then input the current position.

Note: The Forth anti–vibration should be opened before

the end of the push bar will be arrived to avoid the

material was separated from the collet.

2.7XL Generally value:	Setting range: 0~5000	
3.7XL Generally value:	Setting value:	



Parameter description: 5th Anti-Vibration Device open position in working

mode.

Setting method: In manual mode pusher should be pushed forward

until 30~50mm before 5th anti vibration device.

Then input the current position.

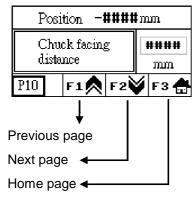
Note: The Five anti–vibrations should be opened before

the end of the push bar will be arrived to avoid the

material was separated from the collet.

2.7XL Generally value: Setting range: 0~5000

3.7XL Generally value: Setting value:



Parameter description: Chuck facing position is the distance between cutters facing detection to cutter facing position.

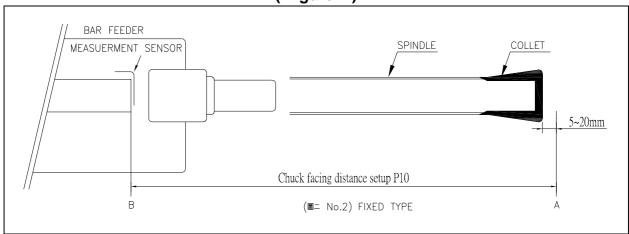
We cannot know if the new bar material has been pushed to chuck facing position until loading a new bar material. (as picture 2)

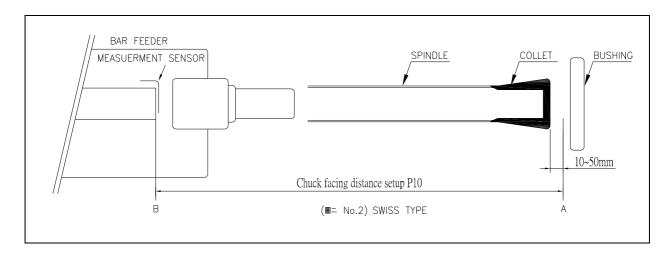
Setting method: According to below drawings to set the distance from A - B point. In addition input it by mm unit.

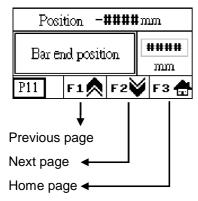
2.7XL Generally value: Setting range: 0~4000

3.7XL Generally value: Setting value:

(Figure 2)

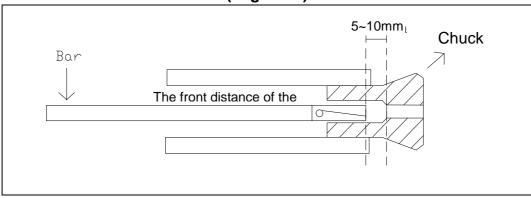


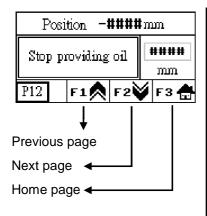




Parameter description: This position is the maximum working limit. If pusher position value is bigger than bar end setting that bar feeder will offer a bar end signal to notice lathe to prepare loading new bar material Setting Mode for fixed lathe: In the manual mode let pusher into lathe spindle until 5~10mm before lathe chuck. Then confirm the value of monitor to input it to be bar end position. Setting Mode for sliding lathe: In the manual operation let lathe spindle move to +Z limit position and pusher move forward until 5~10mm before chuck. Then confirm the value of monitor to input it to be bar end position. Note: Reference figure 3: Be sure to adjust distance indeed to avoid bar end longest or shortest. 2.7XL Generally value: 0~4000 Setting range: 3.7XL Generally value: Setting value:

(Figure 3)





Parameter description: In auto mode the pump stops providing oil position.

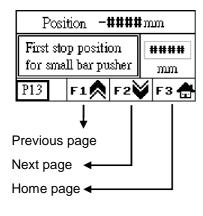
Setting method: In manual mode let pusher move forward to stop

providing oil position. Then input the current

position.

Note: Oil pumps provide oil for lubrication and cooling.

2.7XL Generally value:	Setting range:	0~4000
3.7XL Generally value:	Setting value:	



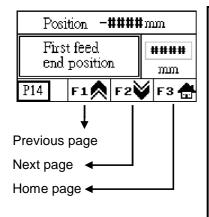
Parameter description: This parameter is to prevent hard impact on new

bar material end because of small pusher block high speed during loading a new bar material. This parameter will let the small pusher block to slow down to prevent hard impact to the new bar

material.

Setting method: Input the required position.

2.7XL Generally value:	Setting range: 0~4000
3.7XL Generally value:	Setting value:



Parameter description: The pre-feeding pusher will push the bar material

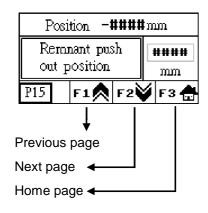
forward until the bar material can go into collet

smoothly when bar pusher is up.

Setting method: Push pre-feeding pusher to stop position and input

current position.

2.7XL Generally value:	Setting range:	0~2000
3.7XL Generally value:	Setting value:	



Parameter description: This distance is the position that bar pusher pushes

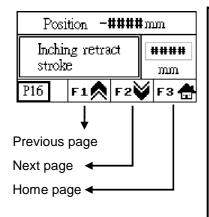
out the remnant into the lathe.

Setting method: Push the pusher to exceed chuck position 20mm

by manual operation. Then confirm the value

showing in monitor and input this value.

2.7XL Generally value:	Setting range: 0~4	4000
3.7XL Generally value:	Setting value:	



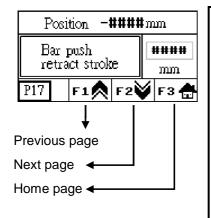
Parameter description: Bar pusher will pull back and inching move forward

when loading a new bar material. This parameter

will control pusher retreating distance.

Setting method: Input the required retreat distance.

2.7XL Generally value:	Setting range:	0~300
3.7XL Generally value:	Setting value:	



Parameter description: If bar pusher position is less than setting value that

pusher will retreat to setting position when chuck

close.

Setting method: Input the required pusher retreating distance.

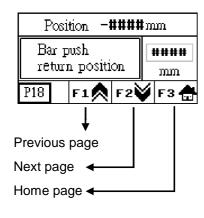
For example: Reference figure 4: If the value of parameter is set

to 30mm and the bar pusher is within the A area, the bar pusher will retract to 30mm after chuck

...

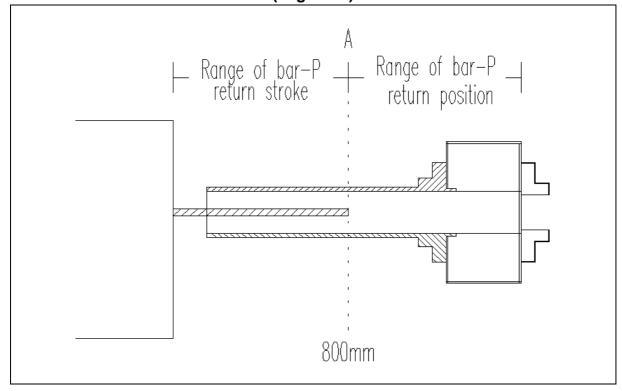
closed.

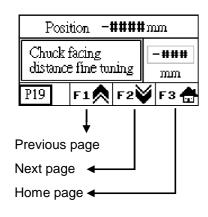
2.7XL Generally value:	Setting range: 0-	-300
3.7XL Generally value:	Setting value:	



Parameter description: If bar pusher position is over than setting value that pusher will retreat to setting position when chuck close. In order to prevent friction and vibration caused from pusher going into the lathe spindle too long. Setting method: By manual operation let the bar pusher move into the spindle inside around 1 / 3 of its length. To ensure not to touch the spindle and input the current position. For example: Reference figure 4: If the value of parameter is set to 800mm and the bar pusher is out of the A area, the bar pusher will retract to 800mm after chuck closed. 2.7XL Generally value: 0~3000 Setting range: 3.7XL Generally value: Setting value:

(Figure 4)





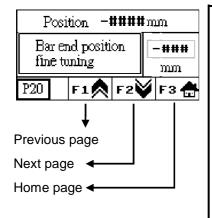
Parameter description: Fine tuning for bar end position based on chuck

facing position. If the tuning value is bigger than 200mm that please amend cutter facing position

directly.

Setting method: Input the required value.

2.7XL Generally value:	Setting range:	-200~200
3.7XL Generally value:	Setting value:	



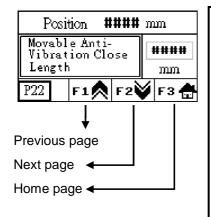
Parameter description: Fine tuning for bar end position based bar end

position. If the tuning value is bigger than 200mm

that lease amend bar end position directly.

Setting method: Input the required value.

2.7XL Generally value:	Setting range:	-200~200
3.7XL Generally value:	Setting value:	



Parameter description: Under Auto-Mode, Anti-vibration Device will close

when bar pusher reached this parameter setup

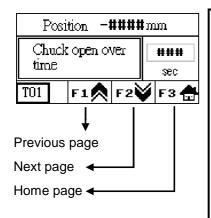
position.

Setting method: Input the required length.

Note: To disable this parameter function, set the value to

zero.

J		
2.7XL Generally value:	Setting range: 0~200	0
3.7XL Generally value:	Setting value:	



Parameter description: The timing is over the time for chuck opened under

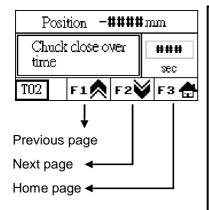
automatic mode and ALARM 29 will display and

stop operating.

Setting method: When the setting value is 0, the parameter function

will be disabled.

2.7XL Generally value:	Setting range:	0~999
3.7XL Generally value:	Setting value:	



Parameter description: The timing of chuck closed is over time under

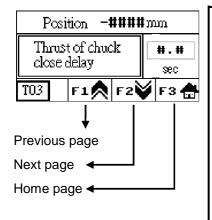
automatic mode. The ALARM 32 will display and

stop operating.

Setting method: When the setting value is 0, the parameter function

will be disabled.

<u> </u>		
2.7XL Generally value:	Setting range:	0~999
3.7XL Generally value:	Setting value:	



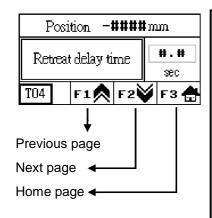
Parameter description: In automatic working mode, pusher pushes bar

material into lathe and chuck close to work. To ensure that material will not move during the chuck close. Set the delay time for bar pusher to change

the speed and torque.

Setting method: Input the required time.

2.7XL Generally value:	Setting range:	0~9.9
3.7XL Generally value:	Setting value:	



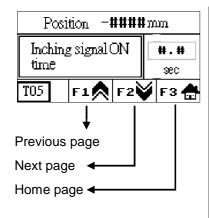
Parameter description: Sets delay time to stop the bar pusher drawing

back so that the bar feeder can run the changing new bars process while the bar end signal and

chuck open signal display from Lathe.

Setting method: Input the necessary delay time.

2.7XL Generally value:	Setting range:	0~9.9
3.7XL Generally value:	Setting value:	

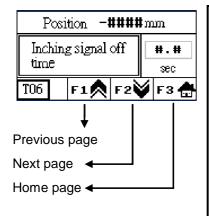


Parameter description: Set the starting time (ON) of bar pusher inching

moves so that the chuck of lathe will move at the same time during bar feeder changes new bars.

Setting method: Input required time.

2.7XL Generally value:	Setting range:	0~9.9
3.7XL Generally value:	Setting value:	



Parameter description: Set the ending time (OFF) of bar pusher inching

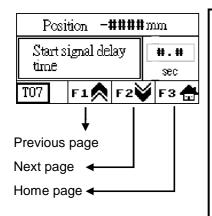
moves so that the chuck of lathe will stop moving at

the same time during bar feeder changes new

bars.

Setting method: Input required time.

2.7XL Generally value:	Setting range:	0~9.9
3.7XL Generally value:	Setting value:	



Parameter description: Delay the time for sending the signal of the new bar

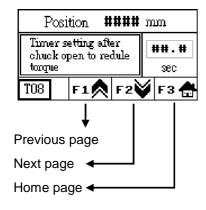
change finished after new bar pushed to chuck

facing position.

Setting method: If the time sets too long, it may cause lathe standby

time much longer during new bar changing.

2.7XL Generally value:	Setting range: 0~9.9
3.7XL Generally value:	Setting value:



Parameter description: In automatic mode the pre-feeding pusher will push

bar material when the pusher rising. Then anti

vibration device will open when pusher pushes bar

material to touch chuck facing sensor.

Setting method: Input the required length.

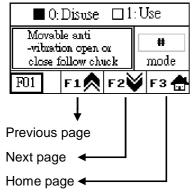
Note: To disable this parameter function, set the value to

zero.

2.7XL Generally value: Setting range: 0~9.9

3.7XL Generally value: Setting value:

6.3.4.2 System function / enter password "258"



Parameter description: Switch either one function of opening or closing the moveable anti-vibration device to accompany the lathe chuck opened or closed.

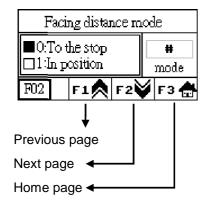
0 - disable
1 - enable

2.7XL Generally value:

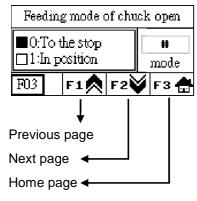
Setting range: 0~1

3.7XL Generally value:

Setting value:



Parameter description: Select either one mode of bringing a new bar to facing position automatic or a new bar pushed to the setting facing position by bar pusher during bars changed. "0: To the stop": The new bar will be pushed to the chuck facing position and keep pushing until the lathe chuck closed. "1: In position": The new bar will be pushed to the setting chuck facing position by the parameter and the bar pusher will stop right away. 2.7XL Generally value: Setting range: 0~1 3.7XL Generally value: Setting value:



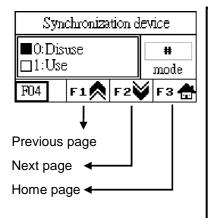
Parameter description: Set either one of modes of bar pusher keeps
feeding or stops feeding a bar to the product
finishing length position under automatic mode
when chuck is open.

"0: To the stop": The bar pusher pushes the bar to the product
finishing position and keeps pushing.

"1: In position": The bar pusher pushes the bar to the product finish
length position and stop pushing.

2.7XL Generally value: Setting range: 0~1

3.7XL Generally value: Setting value:



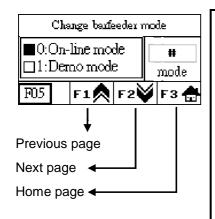
Parameter description: It sets the bar/headstock synchronizing device operation mode.

"0: Disuse": Bar-headstock synchronization is disabled; the bar is continuously driven by the feed motor. For matching with Fixed type CNC.

"1: Activated": Headstock synchronization is on when lathe collet are closed (feed motor stopped), and synchronization is off when lathe collet is open (feed motor running). For matching with Swiss type CNC.

2.7XL Generally value: Setting range: 0~1

Setting value:



Parameter description: Set two modes to normally operate, if set the mode to "0:ON-line mode", bar feeder starts operating along with lathe. If need bar feeder to cycle automatically without connective, please set the mode for "1: Demo mode".

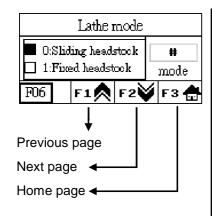
2.7XL Generally value:

Setting range: 0~1

3.7XL Generally value:

Setting value:

3.7XL Generally value:

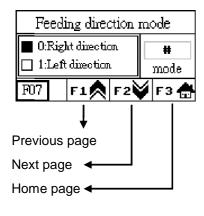


Parameter description: Set the mode for use what kind of type of lathe.

0: Sliding headstock type of lathe

1: Fixed headstock type of lathe

2.7XL Generally value:	Setting range: 0~1
3.7XL Generally value:	Setting value:

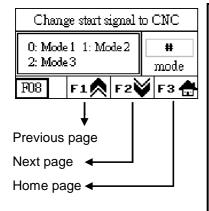


Parameter description: Set the direction of bar feeder fed along with type of lathe.

0: Left feed to right direction

1: Right feed to left direction

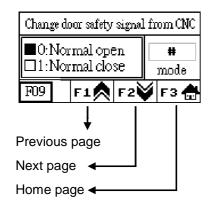
2.7XL Generally value:	Setting range:	0~1
3.7XL Generally value:	Setting value:	



Parameter description: Select modes for output the Cycle start signal of bar feeder.

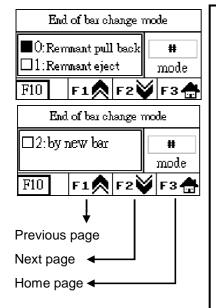
- 0: Under automatic mode, Cycle start signal will send to lathe after bar changed and after bar changed while lathe chuck is opened.
- 1: The cycle start signal will be sent after bar changed.
- 2: Disable.

2.7XL Generally value:	Setting range: 0~2
3.7XL Generally value:	Setting value:



Parameter description: Change the interface signal means safety door
(X23) is abnormal. Change the contacts of NO or
NC circuit of inner program.

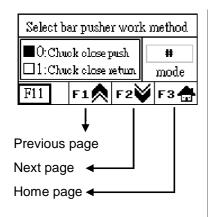
2.7XL Generally value:	Setting range: 0~1
3.7XL Generally value:	Setting value:



Parameter description: Selects different modes for dealing with remnant after bar changed.

- 0: Pull back the remnant into the bar feeder.
- 1: Push out the remnant into the lathe.
- 2: Push out the remnant into the lathe by a new bar when bar end signal is sent and bar feeder will change another new bar.

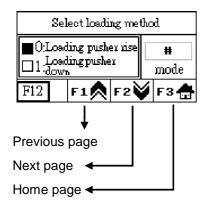
2.7XL Generally value:	Setting range:	0~2
3.7XL Generally value:	Setting value:	



Parameter description: Select the bar pusher forward or backward under automatic mode.

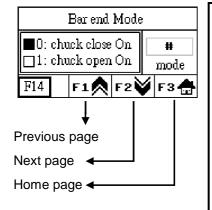
- 0: The bar pusher forward when chuck closed. (Standard)
- 1: The bar pusher backward when chuck closed. (Special)
- If select the parameter 1, must operate with parameter P17 (Bar pusher return stroke) and parameter P18 (Bar pusher return position).

2.7XL Generally value:	Setting range: 0~1
3.7XL Generally value:	Setting value:



Parameter description: The parameter not available.

2.7XL Generally value:	Setting range: 0~1
3.7XL Generally value:	Setting value:

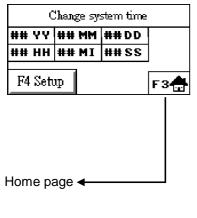


Parameter description: When bar end occurred, the timing for bar feeder sending bar end signal.

0: Chuck close On

1: Chuck open On

2.7XL Generally value:	Setting range:	0~1
	Setting value:	

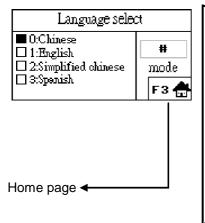


Parameter description: Set the date and time of system to record data.

2.7XL Generally value: Setting range: NO

Setting value:

3.7XL Generally value:



Parameter description: Select the proper language of the information displayed:

0:Traditional Chinese

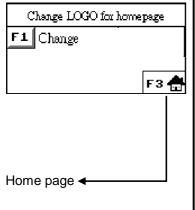
1:English

2:Simplified Chinese

3:Spanish

2.7XL Generally value: Setting range: 0~3

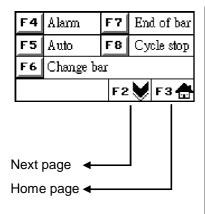
3.7XL Generally value: Setting value:



Parameter description: Shift to display LOGO homepage on the HMI screen.

2.7XL Generally value: Setting range: NO

3.7XL Generally value: Setting value:



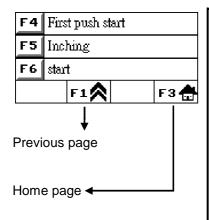
Parameter description: This parameter allows technician to test each signal if it output to lathe after settle down the bar feeder.

Setting method: This parameter only executive under manual mode

both lathe and bar feeder, otherwise it may cause

danger.

2.7XL Generally value:	Setting range: NO
3.7XL Generally value:	Setting value:



Parameter description: This parameter allow technician to test each signal

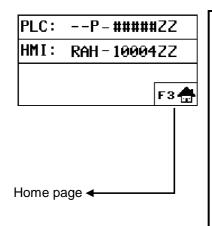
output on interface is continued to lathe.

Setting method: To executive this parameter must be under manual

mode both lathe and bar feeder or could cause

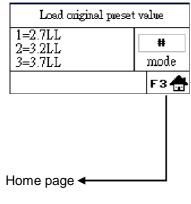
danger.

2.7XL Generally value:	Setting range: NO	
3.7XL Generally value:	Setting value:	



Parameter description: To verify the version number of PLC and HMI programs.

2.7XL Generally value: Setting range: NO
3.7XL Generally value: Setting value:

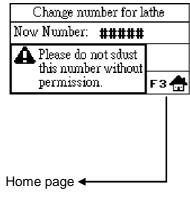


Parameter description: Set all parameters to original value. Select firstly the correct length of bar feeder to operate.

Otherwise may cause problems.

1: 2.7LL
2: 3.2LL
3: 3.7LL
Note: When setting this parameter 1-3, all HMI and timer will return to "0", and then start operating.

2.7XL Generally value: Setting range: 0~3
3.7XL Generally value: Setting value:



Parameter description: For recognizing the number of PLC and HMI programs to suit for lathe model.

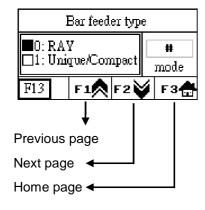
2.7XL Generally value: Setting range: 99999

Setting value:

100

3.7XL Generally value:

6.3.4.3 Special parameter chart



Parameter description: To set the model of loading parameter of bar feeder.

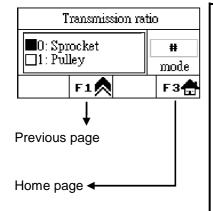
0: RANGER 112

1: Unique / Compact

If normal loading mode is Ray type, then balls crew

loading mode is Unique / Compact.

2.7XL Generally value:Setting range:0~13.7XL Generally value:Setting value:



Parameter Description: To set the model of transmission ratio of bar

feeder.

0: Sprocket mode

1: Pulley mode

Note: The parameter needs the practical transmission

model to be set or it will affect the position

calculated and display wrong data.

2.7XL Generally value:	Setting range: 0~1
3.7XL Generally value:	Setting value:

7. MAINTENANCE RANGER 112

7. MAINTENANCE

7.1 General maintenance





HAZARD-WARNING

Before operators are maintaining the bar feeder, the power must be turned off. In order to make good use of the bar feeder, please maintain the bar feeder regularly.

Accessories and the area of operation must be cleaned to increase the safety of operators.

Using petroleum or other dissolvent to maintain the bar feeder maybe caused damage of cover or plastic components.



INFORMATION

The oxidation will damage the components and electronic equipments. Please pull out the plug and the air joint while the bar feeder is not operated. Keep the air unobstructed in the operation area and the bar feeder can't be covered completely, otherwise there will be produced mist.

7. MAINTENANCE RANGER 112

7.2 Regular maintenance

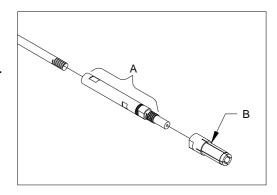
List 1. - Regular maintenance

				Frequ	ency	
Component Action	Action	Hours		Regular	Period	
	200	1250	2500	200	1250	
Collet	Check wear	•				
Guide channel	Check wear and clean		•			
Feeding chain	Lubrication	•				
	Tension	•				
Air cleaner	Check				•	

^(•) Optional

7.2.1 Check the pusher collet and revolving tip

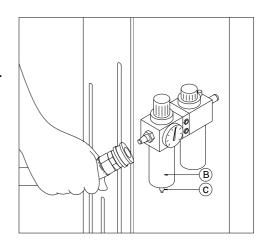
Check that revolving tip (A) rotates smoothly. Check that pusher collet (B) has the correct tension.



7.2.2 Check the air regulator

Check the bottle (B) for water.

Press button (C) to exhaust water out of bottle.



8. CAUSE AND BREAKDOWN AND TROUBLESHOOTING

8.1 Frequent cause of breakdown

ITEM	Cause	Solution	
Unable to start the bar	Without power.	Check the power source.	
Feeder.	In emergency.	Restart.	
The bar feeder is reset but			
the bar feeder can't auto to	The lathe is sending signal.	Check the connection.	
start.			
The device of the	Compressed air is unable to	Chook the air aupply	
compressed air can't work.	be sent.	Check the air supply.	

8.2 Breakdown on frame device

Situation	Cause	Solution
Material are unable to load	The position of plates are too	Adjust the position of plates.
on the frame device.	low.	Aujust the position of plates.

8.3 Breakdown on the collect

Situation	Cause	Solution	
Material is unable to be inserted into the collet	The adjustment of the clamp	Re-adjust.	
	device is not correct.	Ne-adjust.	
	The diameter of collet and	Change a new collet.	
	material are different.		
	The end of the material is too	Chamfering before feeding	
	rough.	material.	
	The air pressure is without	Charle tha mrangura	
	chamfer.	Check the pressure.	

8.4 Breakdown on feeding material

Situation	Cause	Solution	
Material can't feed into the	The center of the bar feeder	Do adjust the center	
spindle smoothly	and the lathe isn't correct	Re-adjust the center	
Material can't feed into the	The front of the material is	Chamfering before feeding	
chuck of the lathe smoothly	too rough.	material	

8.5 Refer alarm message

8.5.1 HMI Alarm Message

ERROR / CAUSE	CURE
ALARM-01 F3 Push bar can't reteat to the origin during the period of changing a new material.	
▲ ALARM-02 F3 ♣ Long feed safety.	Please check the value of long feed safety is correct.Check the turret whether it is at correct position of stopping material.
ALARM-03 F3 🚓 Short feed safety.	Please check whether the setting value of shortest length would be proper.Check the turret whether it is at correct position of stopping material.
The chuck close during the period of changing a new material.	
ALARM-05 F3 🚓 Remnant has not pull out yet.	
ALARM-06 F3 🚓 Lathe alarm.	%Check chuck why the chuck not close. By auto mode. %Before machining, please solve the alarm of CNC.
ALARM-07 F3 A	Check remnant whether get stuck in the collet or clamping stand.Remnant don't take out from finger.
Overtake the rise time of the push bar.	

ERROR / CAUSE	CURE
Overtake the down time of the push bar.	
Facing detection is breakdown (S04).	
Overtake the safety time of first feeding.	Check the setting value of S04 or Q04.Check whether to have the foreign matter to catch.
A ALARM-12 F3 ♣ Without material.	Check bars whether left in the plate.Check material whether rush out the clamping stand when first feeding.Check any bar inside guide channel or no
Overtake the time of clamp retreat.	
ALARM-14 F3 🚓 Overtake the time of clamp go forward.	%Check air pressure.%Check LS05 whether breakdown or loose.
▲ ALARM-15 F3 ♣ Material is too short.	
ALARM-16 F3 A Material is unable into the lathe smoothly.	
ALARM-17 F3 A When the bar feeder send start signal, the lathe isn't running.	**Check the alarm No. on LCD display of servo whether it is abnormal. If yes, please inform the relevant technician about abnormal code to analyze reasons.

ERROR / CAUSE	CURE
ALARM-18 F3 🚓 LS7 and LS8 at the same time "ON".	
ALARM-19 F3 🚓 LS6 and S05 at the same time "ON".	∴ Check LS05 and LS06 whether breakdown or loose.
ALARM-21 F3 🚓 Servo is breakdown.	Check the alarm No. on LCD display of servo whether it is abnormal. If yes, please inform the relevant technician about abnormal code to analyze reasons.
ALARM-22 F3 AB Bar feeder has not been auto status when CNC is running.	Check the bar feeder was in auto status when CNC is machining normally, otherwise bar feeder can't feed material.
ALARM-23 F3 🚓 Pump is breakdown.	
ALARM-24 F3	
ALARM-25 F3 ATTHE Safety cover is not close.	
ALARM-26 F3 de Cutting sensor error S04.	
Air pressure inadequate.	

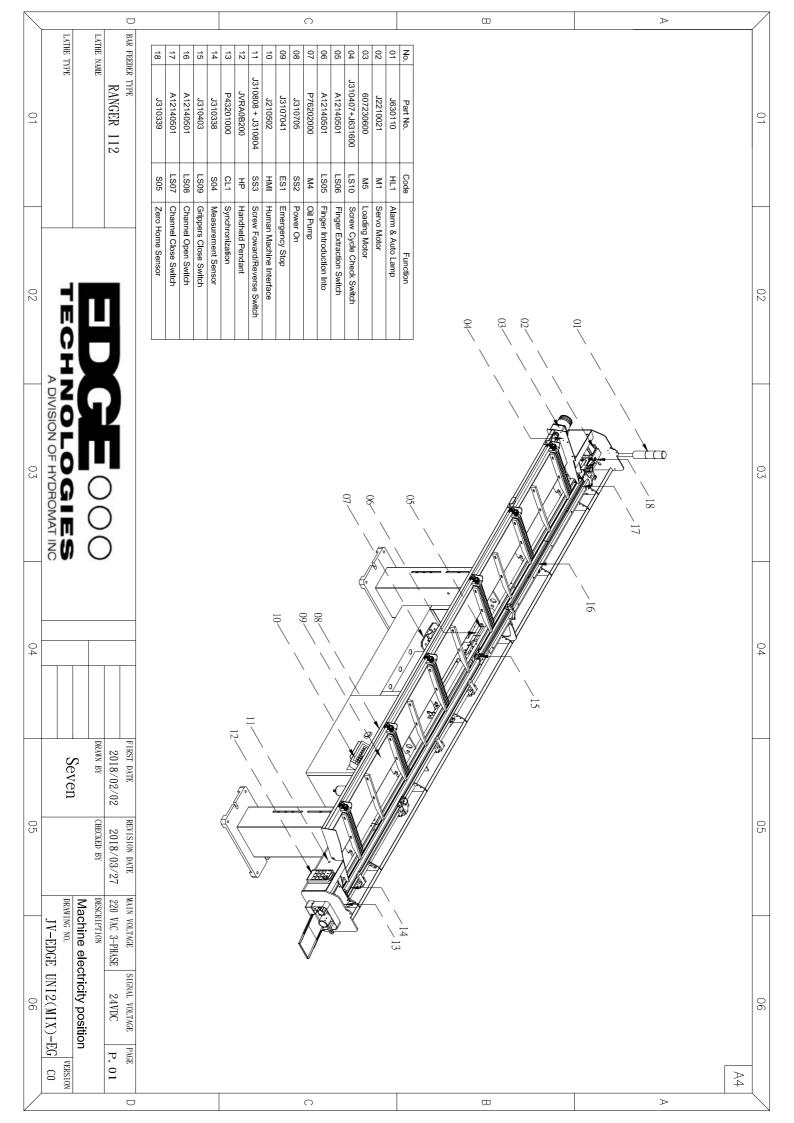
ERROR / CAUSE	CURE
▲ ALARM-28 F3 ♣ Emergency stop.	
ALARM-29 F3 A	
ALARM-30 F3 🚓 Chuck open pushbar forward.	
ALARM-31 F3 🚓 Chuck open pushbar retreat.	
ALARM-32 F3 🚓 Chuck close overtake time.	
▲ ALARM-33 F3 ♣ Lathe emergency stop.	※Pease loose Emergency stop button.
▲ ALARM-34 F3 ♣ Motor power no open	
▲ ALARM-35 F3 ♣ matrial change time over.	
ALARM-36 F3 Loading bar detection switch or loading bar motor failure.	*Please check if the sensor is short or not when screw bar is running.*Please check if loading moter is running or not.

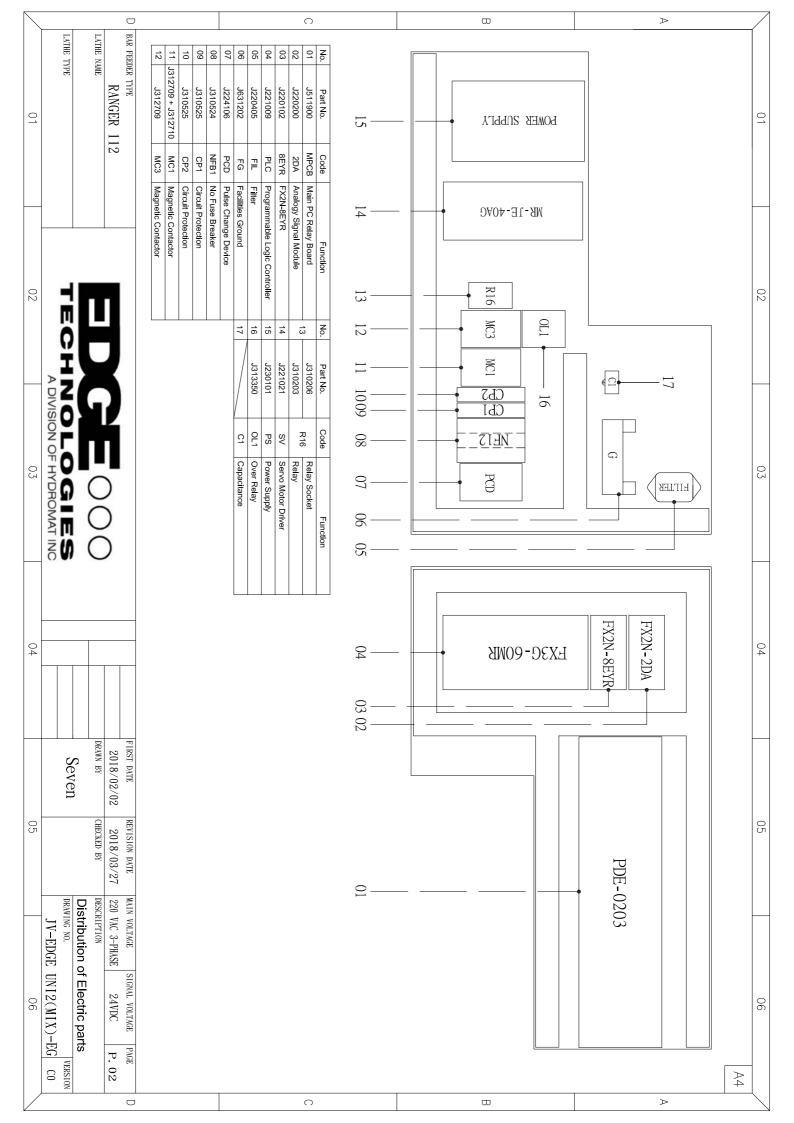
8.5.2 Servo alarm message

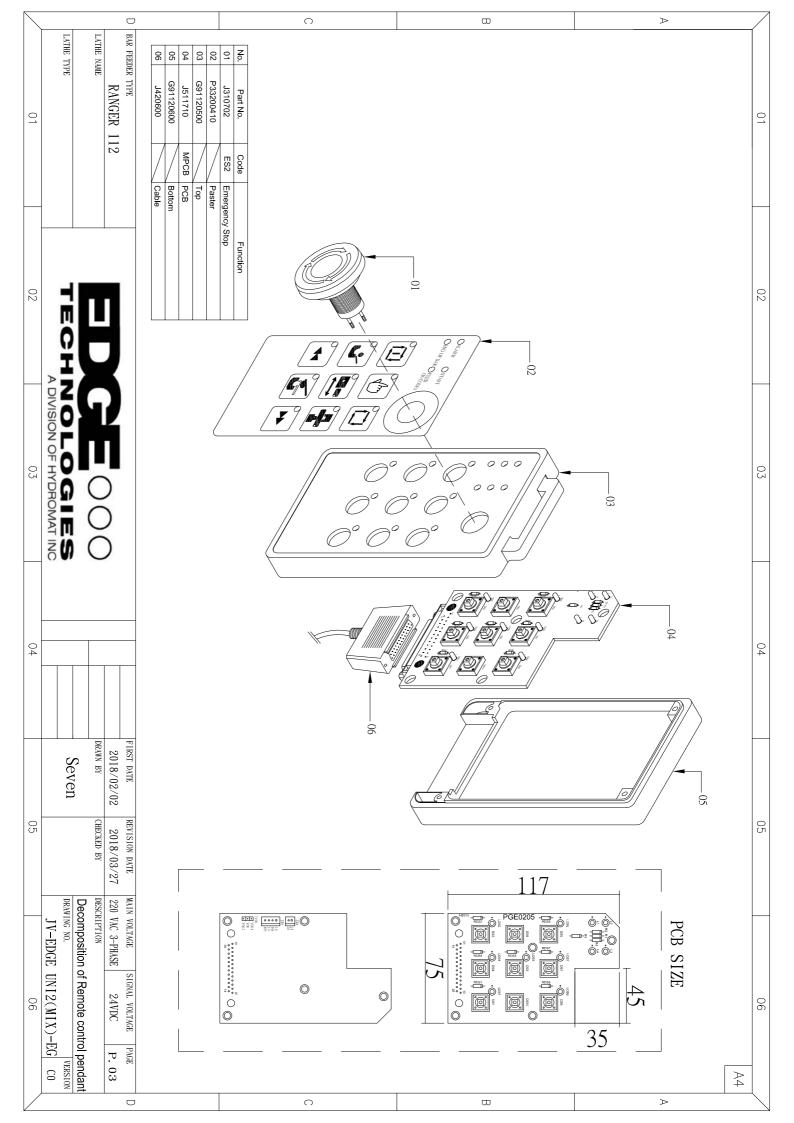
	LIST OF SER	VO DRIVER ALARM
	Display	Name
	AL. 10	Under voltage
	AL. 12	Memory error 1 (RAM)
	AL. 13	Clock error
	AL. 15	Memory error 2 (EEP-TOM0)
	AL. 16	Encoder error 1
	AL. 17	Board error 2
	AL. 19	Memory error 3 (Flash-ROM)
	AL. 1A	Abnormal motor assembly
	AL. 20	Encoder error 2
	AL. 24	Abnormal main circuit
	AL. 25	Absolute position erase
	AL. 30	Regenerative error
ALARMS	AL. 31	Overspeed
ALAKWIS	AL. 32	Overcurrent
	AL. 33	Overvoltage
	AL. 35	Command pulse frequency alarm
	AL. 37	Parameter error
	AL. 45	Main circuit high heat
	AL. 46	Servo motor overheat
	AL. 47	Abnormal cooling fon
	AL. 50	Overload 1
	AL. 51	Overload 2
	AL. 52	Error excessive
	AL. 8A	Overtime
	AL. 8E	error
	88888	Watch dog

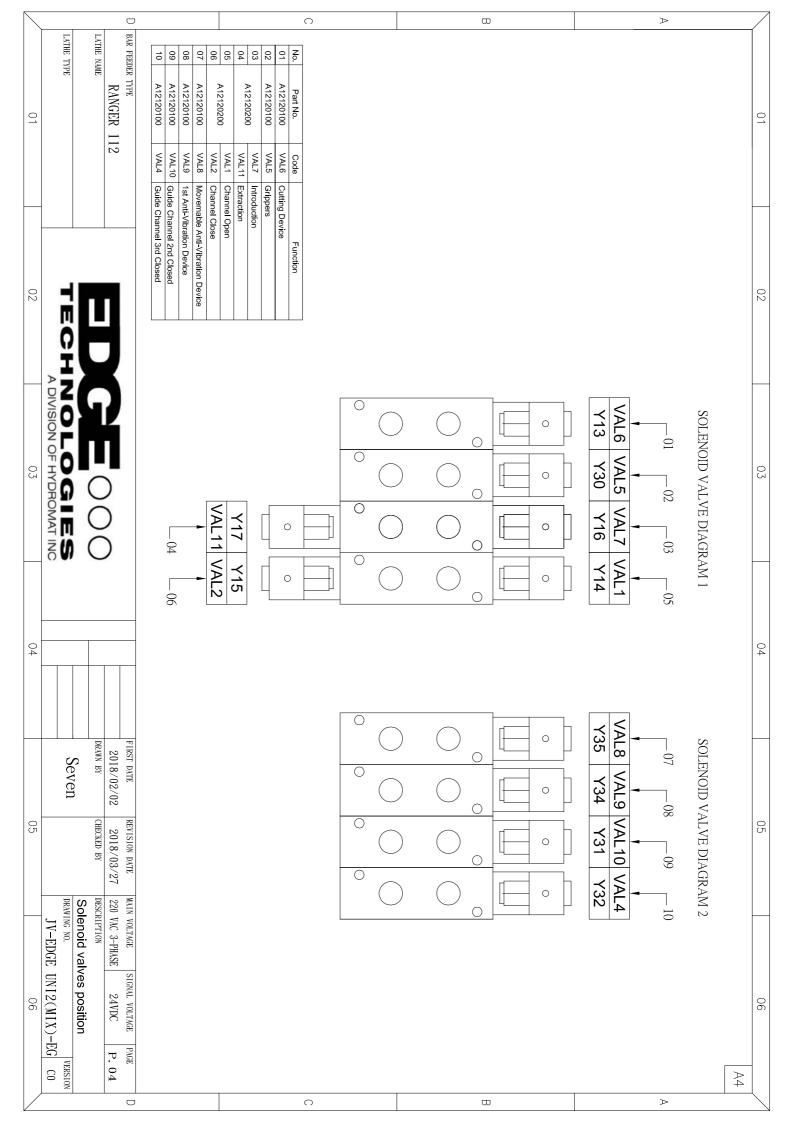
8. CAUSE AND BREAKDOWN AND TROUBLESHOOTING

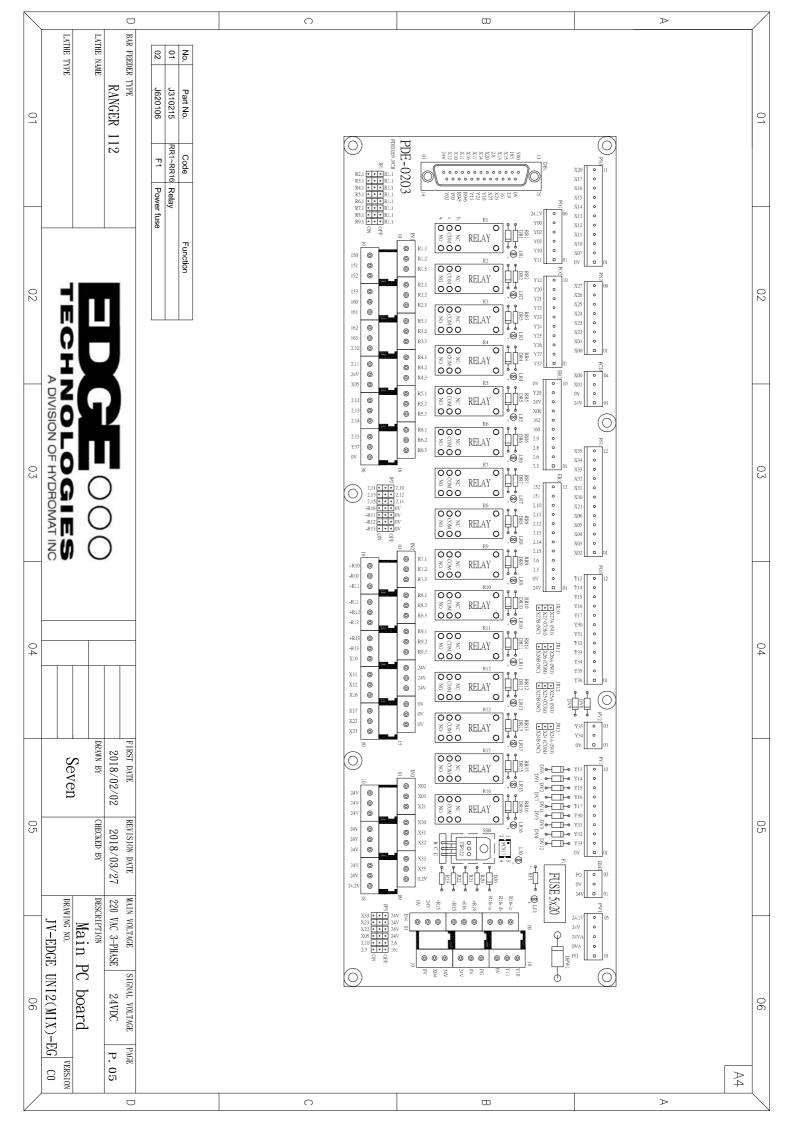
	Display	Name
	AL. 92	Open battery cable warning
	AL. 96	Zero setting error
	AL. 99	Limit alarm
	AL. 9F	Battery warning
	AL. E0	Excessive regenerative load warning
	AL. E1	Overload warning
WARNINGS	AL. E3	Absolute position counter warning
WARNINGS	AL. E5	ABS time-out warning
	AL. E6	Servo emergency stop
	AL. E8	Cooling FAN low rpm alarm
	AL. E9	Main circuit off warning
	AL. EA	ABS SV ON warning
	AL. EC	Over load alarm 2
	AL. ED	Torqut word over

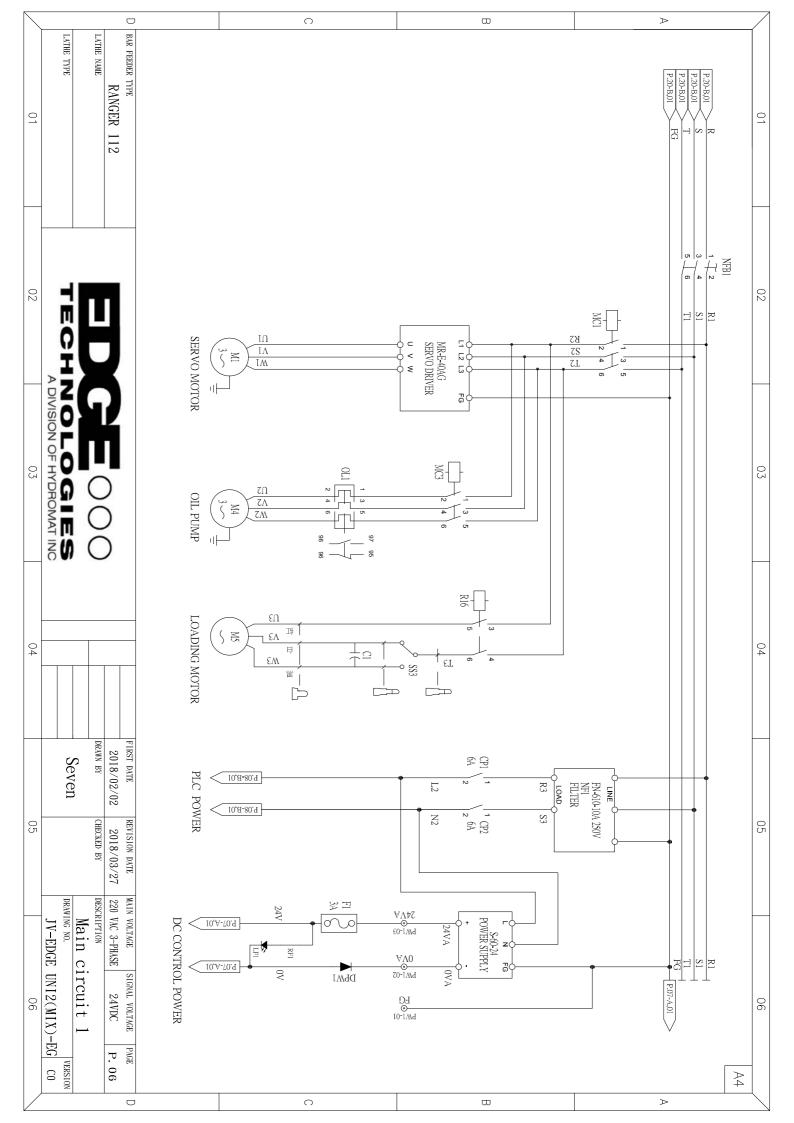


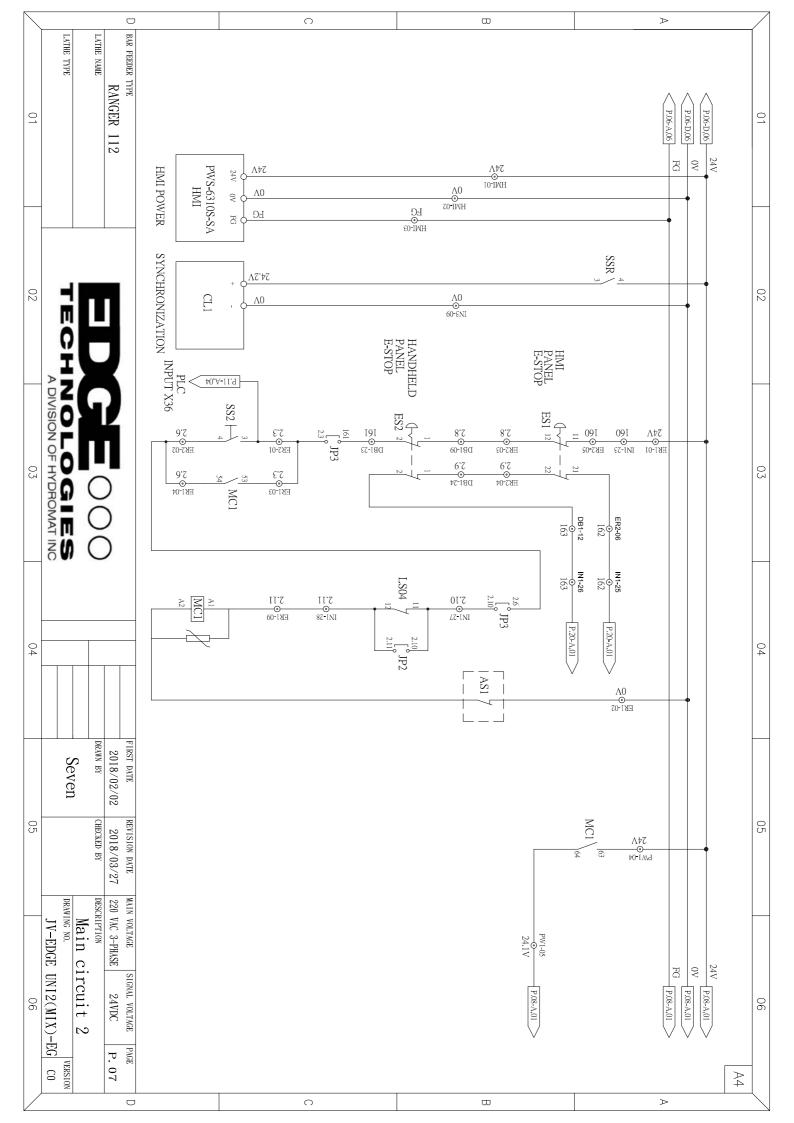


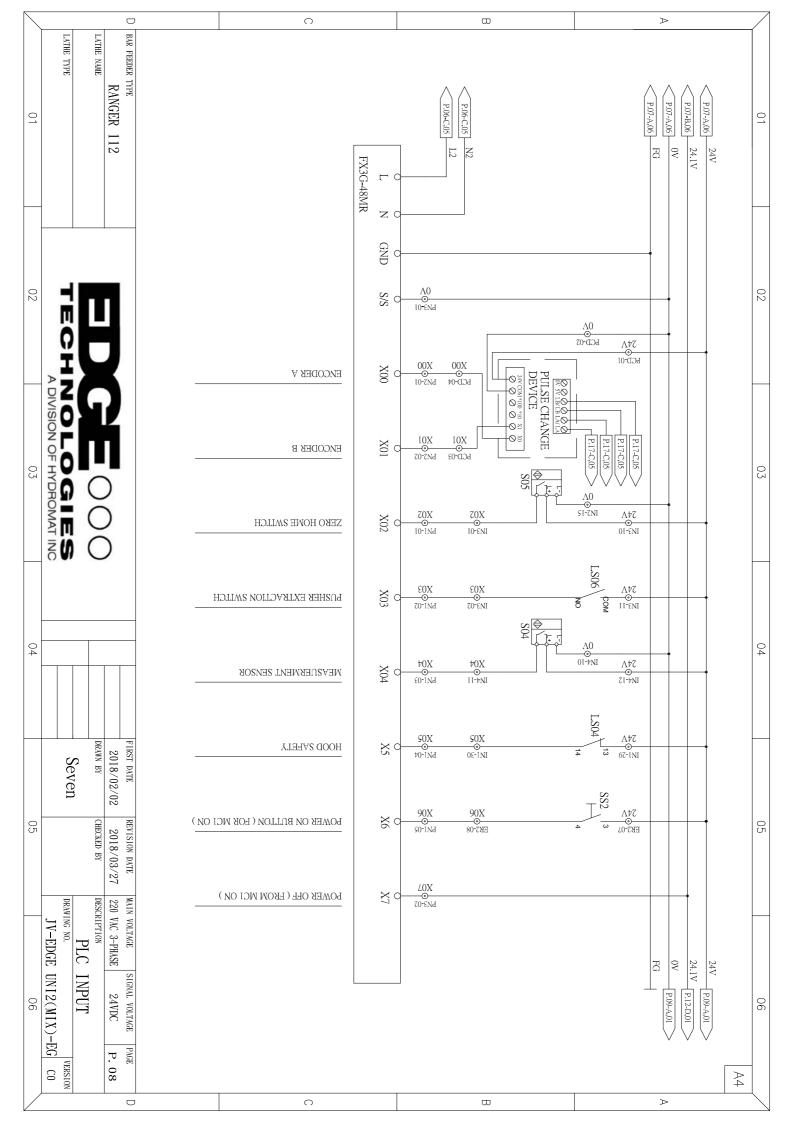


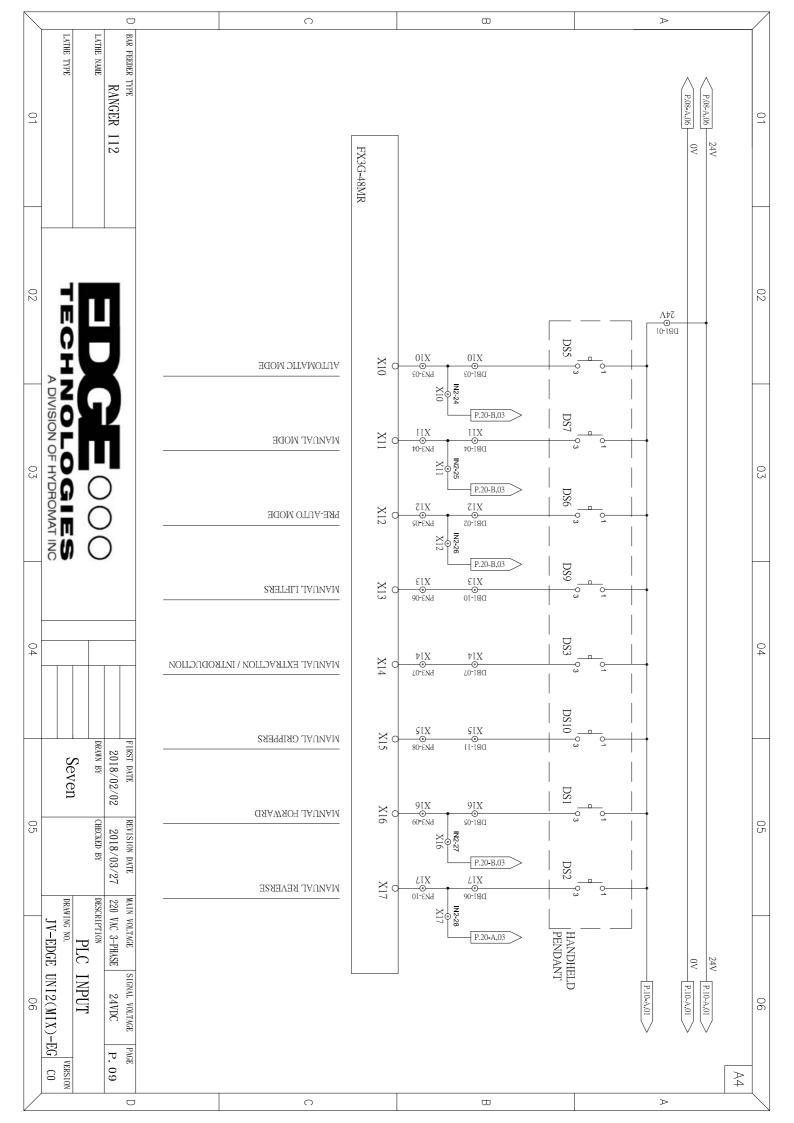


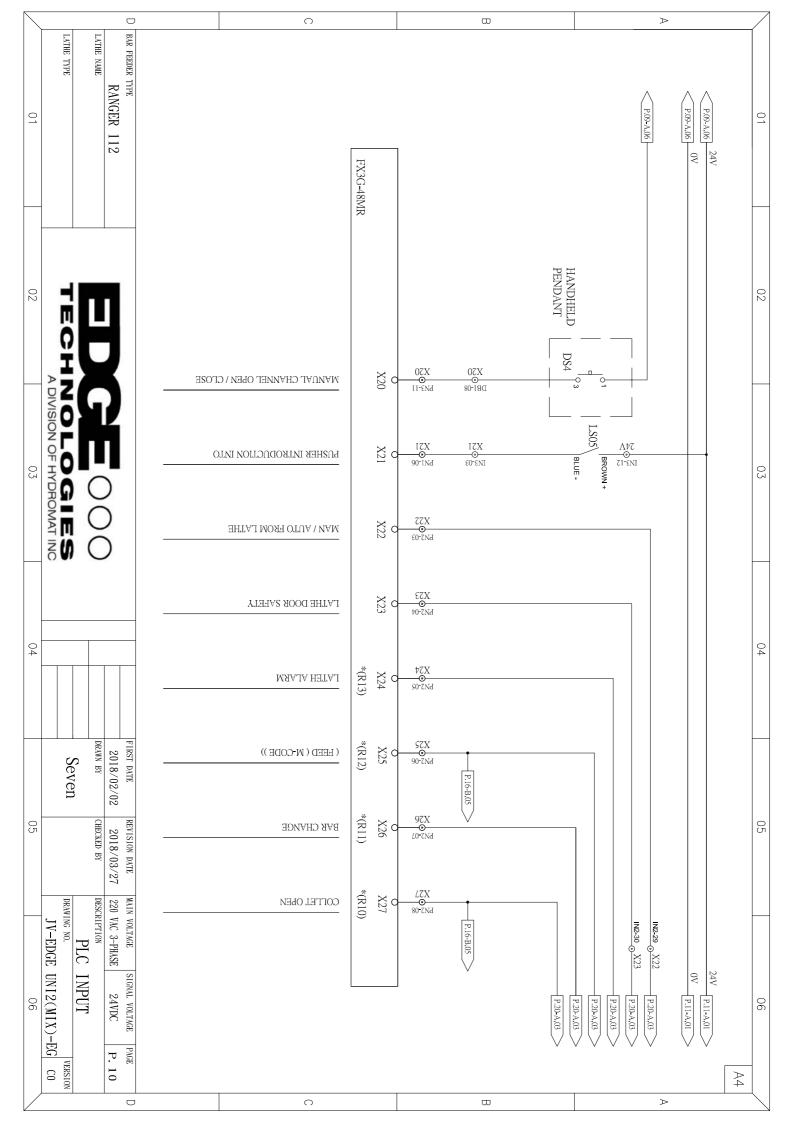


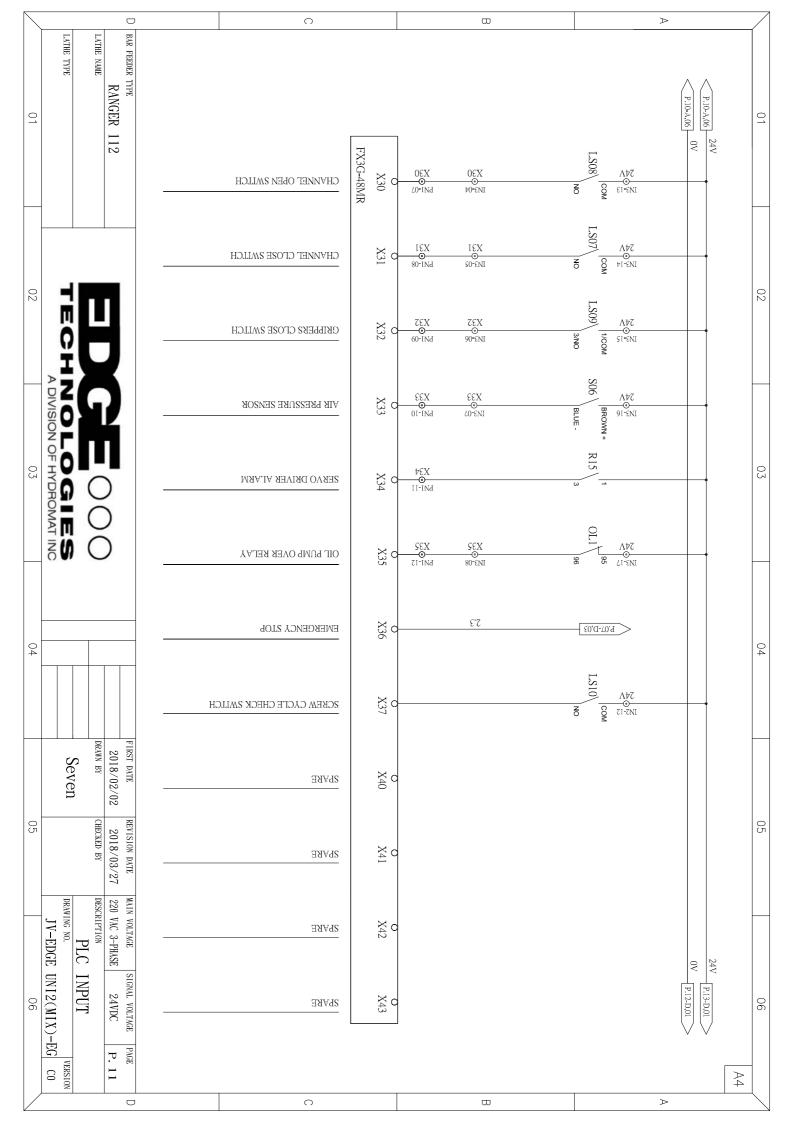


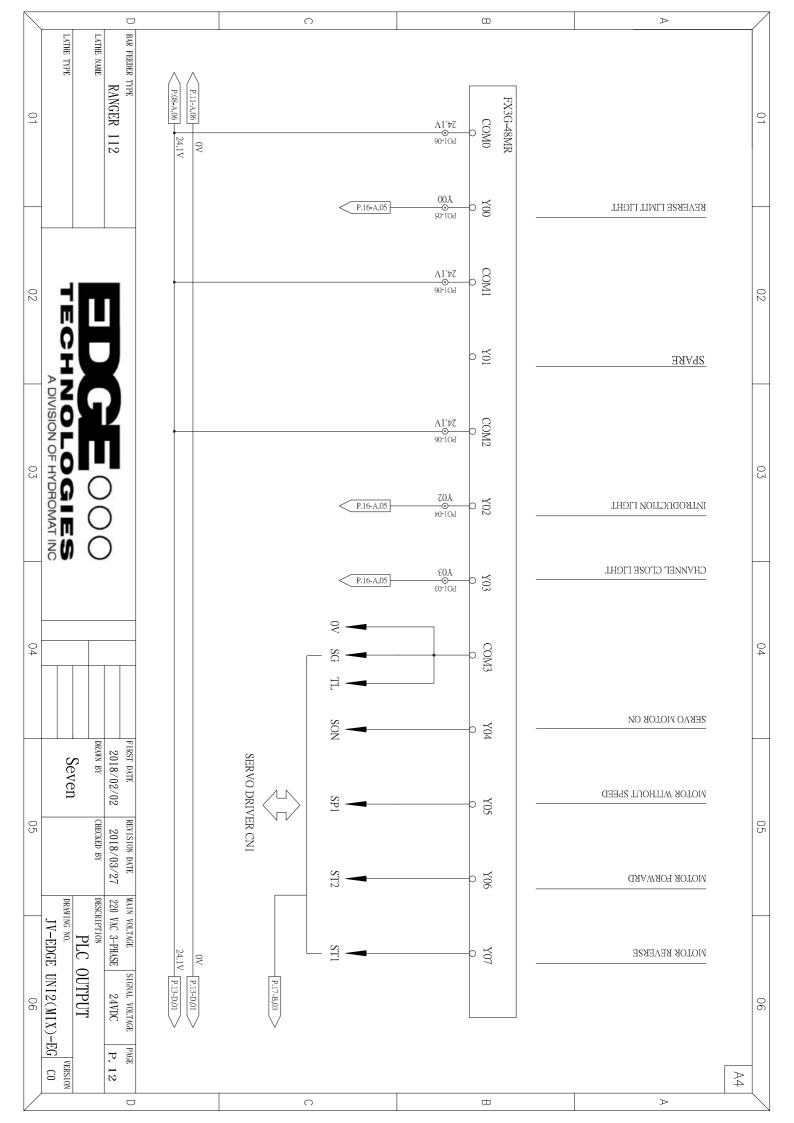


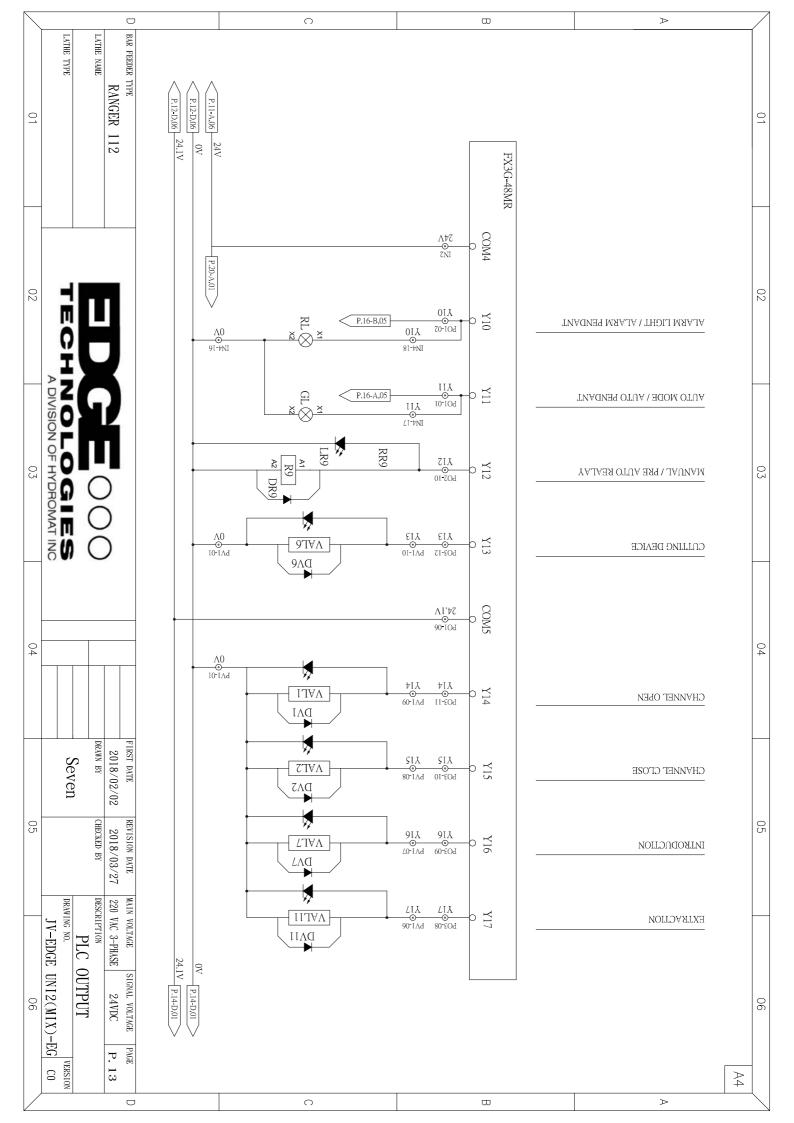


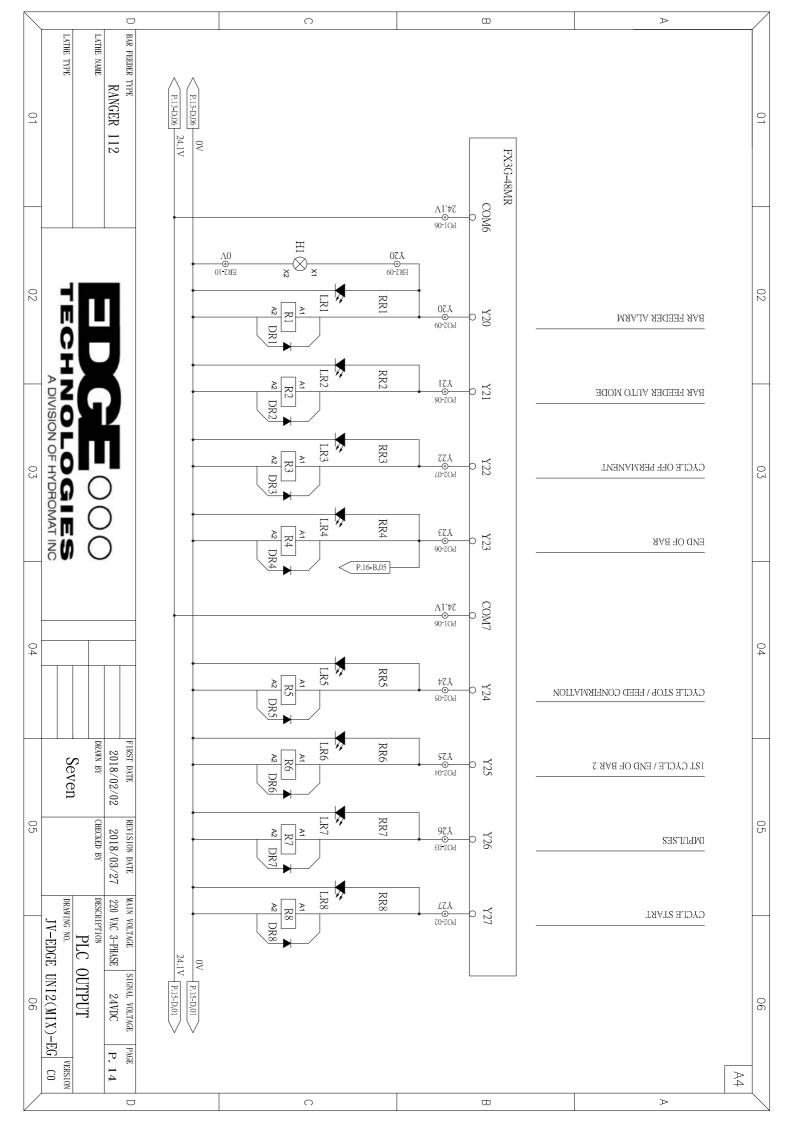


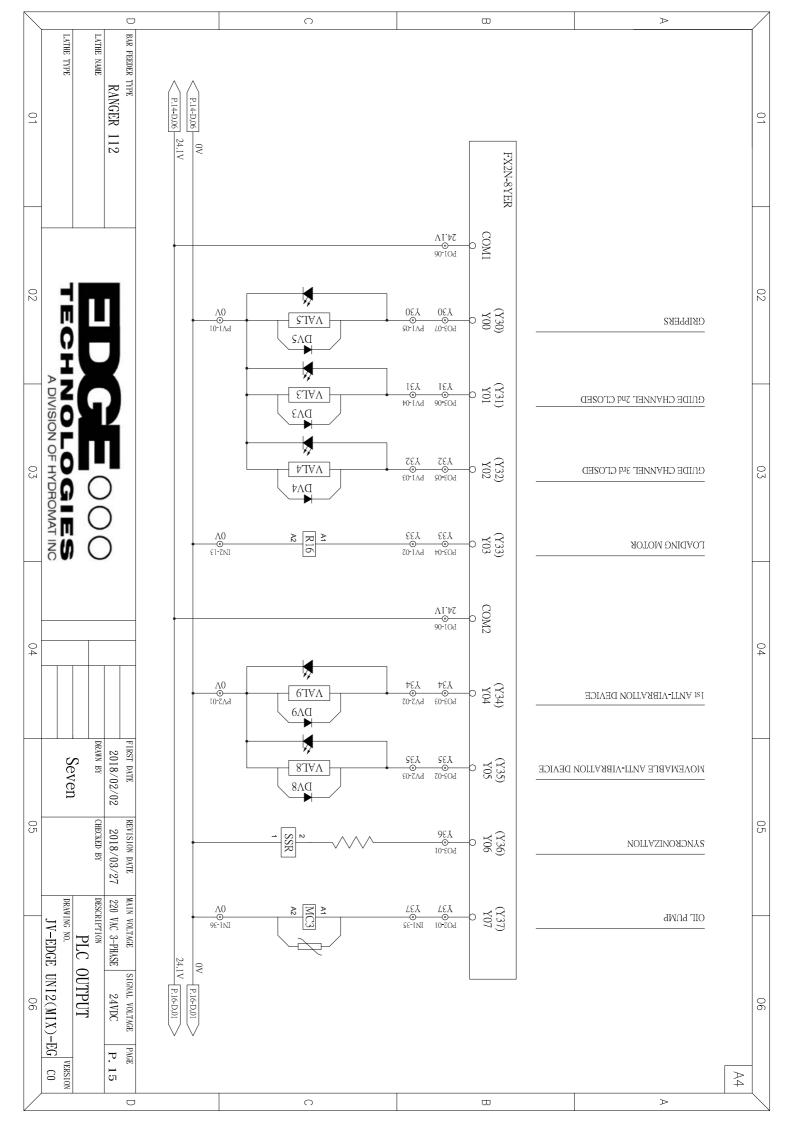


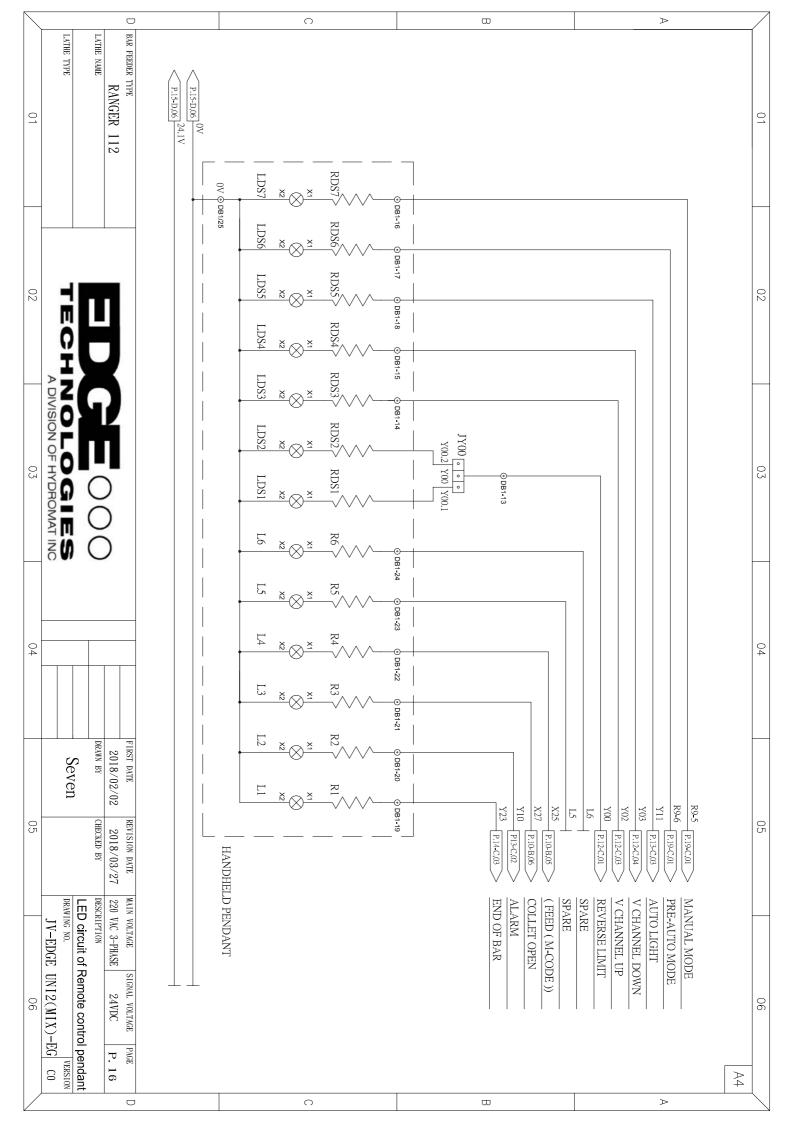


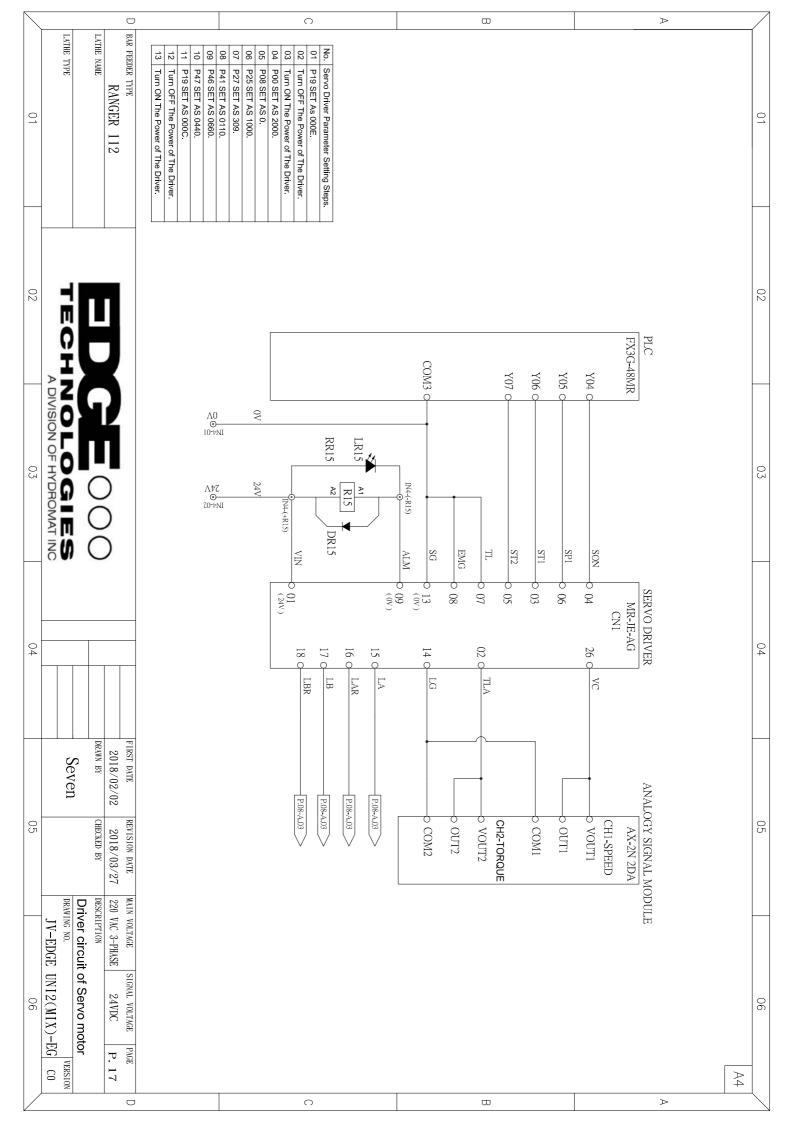


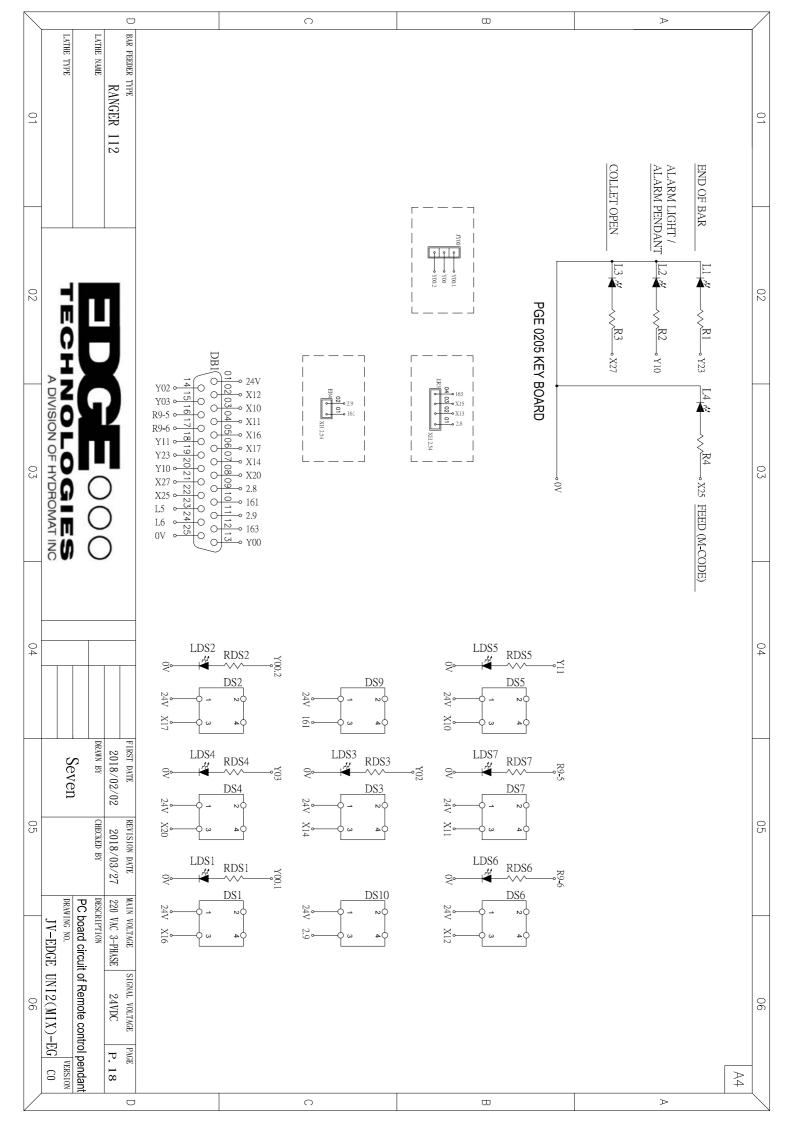


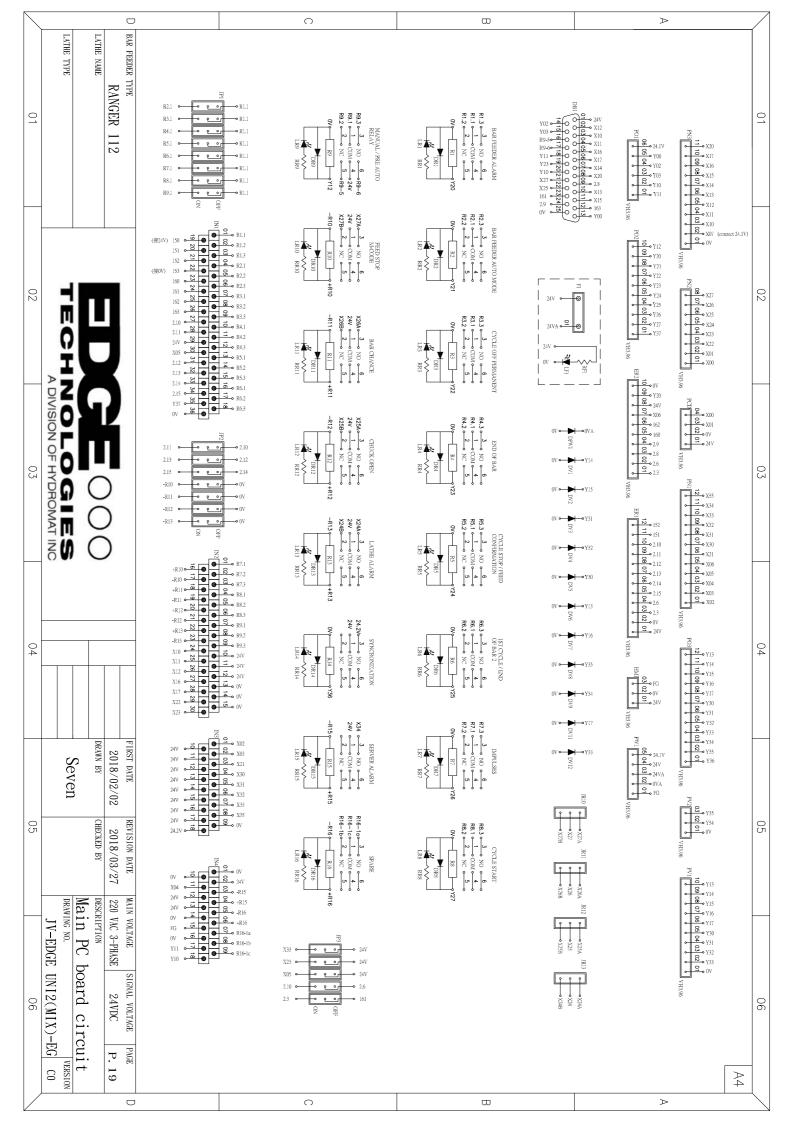


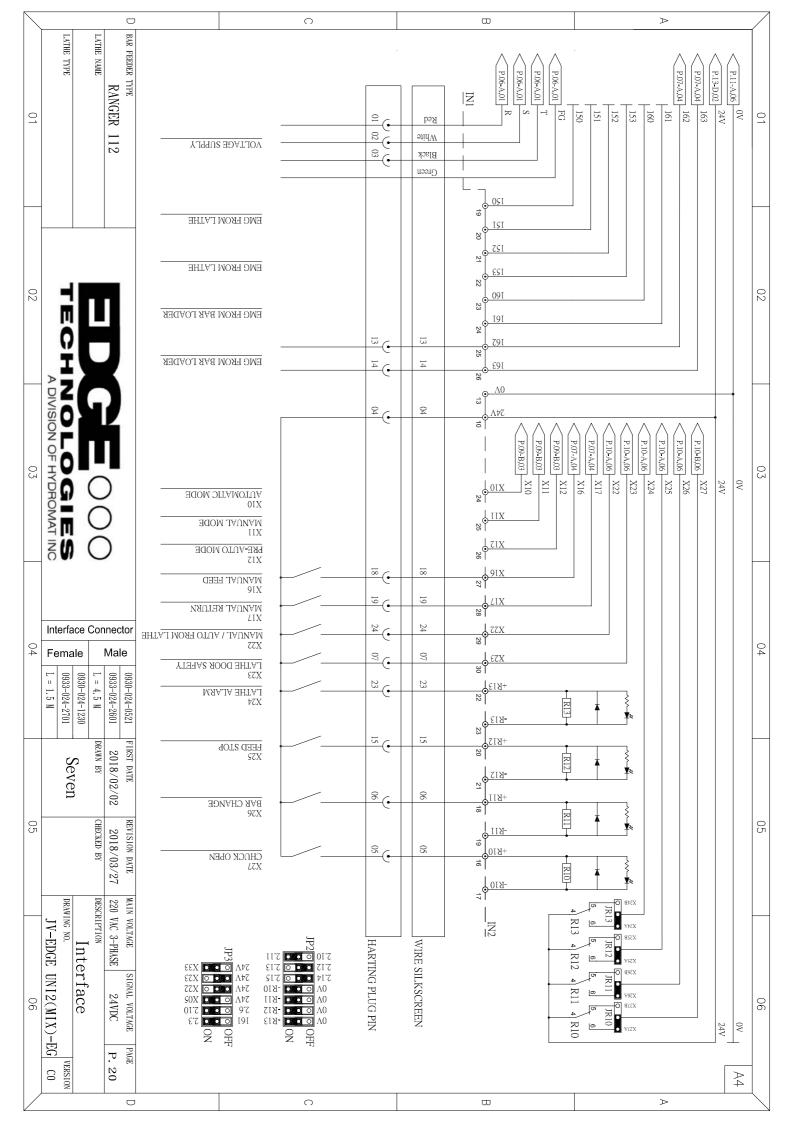


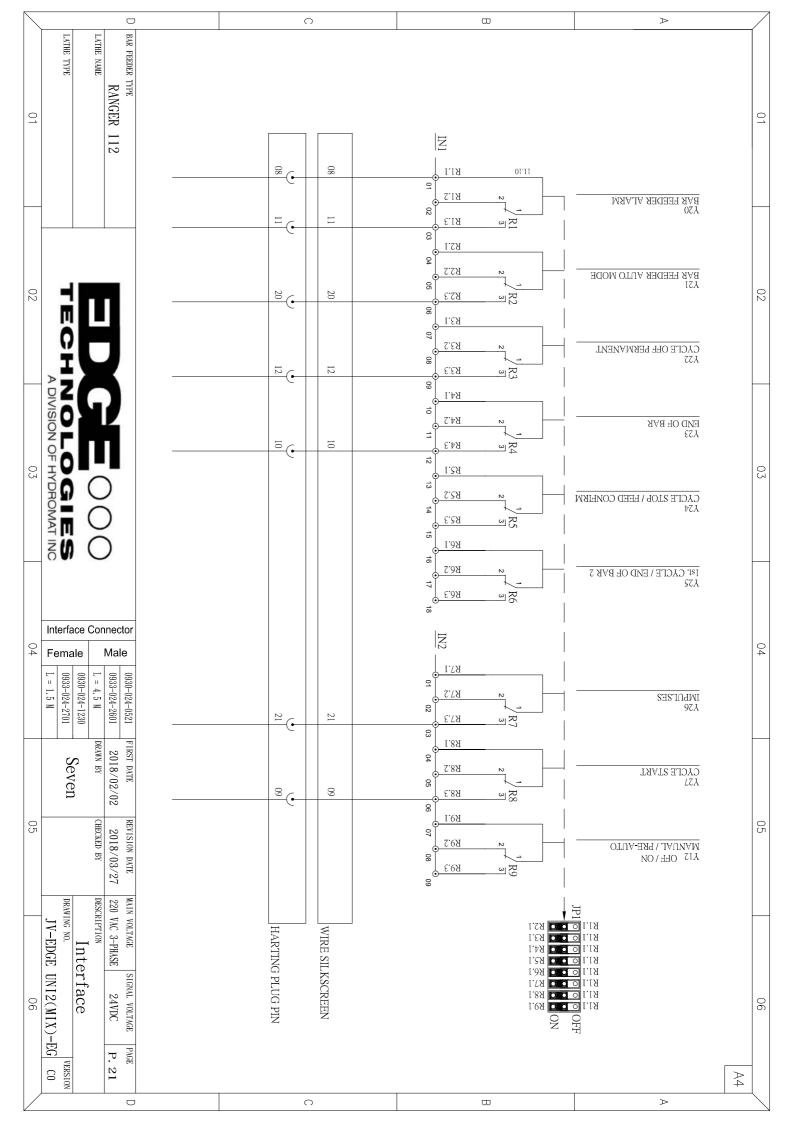












RANGER 112	100 SYCHRONIZATION DEVICE TELESCOPIC FRONT NOSE / FIXED FRONT NOSE	080 ANTI-VIBRATION DEVICE	070 BAR PUSHER UNIT	060 GUIDE CHANNEL UNIT	050 CUTTING DEVICE	040 FEEDING DRIVER UNIT	030 MAIN STRUCTURE	020 CLAMP DEVICE	010 MAGAZINE	040 070
FIGURES INDEX		030 —								
000 <u>2</u>		080		010						090

RANGER 112 3 2 z 6 RA26MA3038 RA26MA3400 RA26MA2700 RA26MA2900 RA26MA3100 RA26MA3810 RA26MA2800 RA26MA2600 RA26MA2500 RA26MA3900 RA26MA3337 RA26MA3037 RA26MA3327 RA26MA3038 RA26MA3028 RA26MA3027 607230600 J310407 Code 27 6 Ŋ 9 S 10 5 QTY 37 12-4 22 Motor Block Holder Magazine frame (Right operating)
2,7M
Magazine frame (Right operating)
3,7M
Magazine frame (Left operating) Magazine frame 3.7M Rack Screw Hex Gear 10-Limit switch Timer cam Coupling Support Rod 3.7M L=3550 Rod 2.7M L=2540 Spacer 2.7M Magazine frame (Left operating) 3.7M 13-Denomination MAGAZINE 9 Right operating Left operating

22 21 23 20 15 14 24 18 17 16 3 2 Right operating 10 9 × 24 RA26GR000A RA26GR001A RA26GR1400 RA26GR0300 RA26GR1100 RA26GR1300 RA26GR0200 RA26GR0210 RA26GR0310 RA26GR0140 RA26GR0130 RA26GR1900 RA26GR0900 RA26GR0700 RA26GR0510 RA26GR1200 RA26GR0600 RA26GR0410 RA26GR0800 RA26GR1000 A12140501 A13120100 A11131800 A11131801 J310403 Code ρŢ N N Bushing Base Plate Plate Plate Plate Clamp device (Left operating) Clamp device (Right operating) Anchor Switch D2VW-5-1M Bushing MIcroswitch LY-67A-5N Arbor Arbor Clip cutter Clip cutter Anchort (L) Sliding plate Sliding plate Sensor shaft Support Bended connector SPL 6-02 Cylinder SDAS-50x30 Cylinder SDA-50x30 Anchort (R) Denomination Left operating 5 12 $\frac{1}{2}$ 10-19 -23 င်္ပ

2

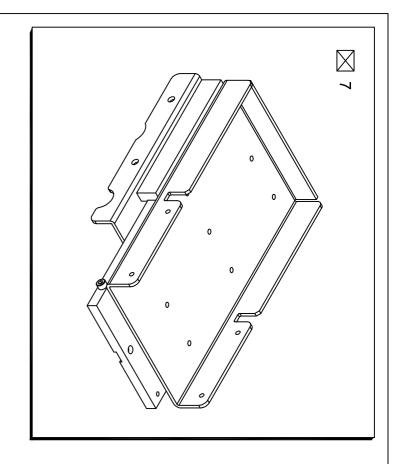
RANGER 112

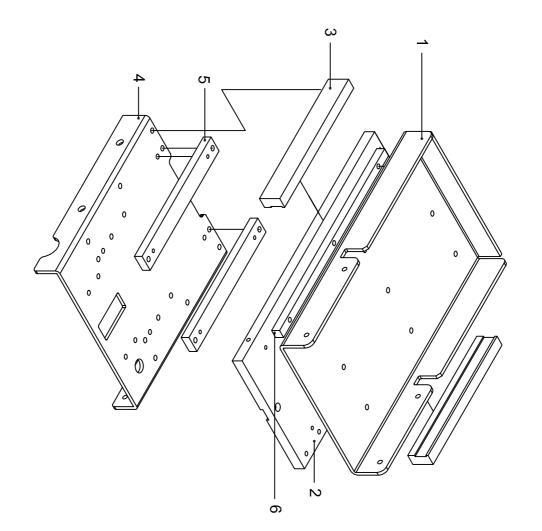
CLAMP DEVICE

030 3	MAIN STRUCTURE		112	RANGER 112	RA
		Cover	_	RA26BA3210	22
		Hinge	1 2	G8112000A	21
		Plate	2	AV51BA3500	20
		Screw	1	RA26BA2900	19
	7—7	Cover	2	RA26OL0510	18
		Pump		RA26OL0401	17
	6	Remain box		P76200500	16
		Plate		RA26OL0200	15
	13 /	Oil tank	_	RA26OL0100	14
0	14	Panel	2	P76200604	13
-		Adjustable stand	2	P76200100	12
		Cover	1	RA26BA1200	11
		Cover		RA26BA1100	10
		Oil recever		RA26BA1000	9
		Oil recever	1	RA26BA0900	8
		Lower stand	2	RA26BA0800	7
		Electrical cabinet		P76200602	6
—10		Cover 3.7M	1	RA26BA3020	ر
		Cover 2.7M		RA26BA3030	ת
		Cover		RA26BA3000	4
		Rear cover 3.7M	2	RA26BA020437	U
4->/// / //		Rear cover 2.7M	2	RA26BA020427	ა
		Handle	2	RA26BA0401	2
		Main structure (Left operating) 3.7M	1	RA26BA0238	
		Main structure (Left operating) 2.7M	_	RA26BA0228	-
		Main structure (Right operating) 3.7M		RA26BA0239	
		Main structure (Right operating) 2.7M		RA26BA0229	
		Denomination	QTY 27 37	Code	z
		,			
		5			
		7			
		22			

RANGER 112 5 14 13 12 11 10 16 9 ω 17 RA26MZ000A ZS06060620 BSF2815 RA26MZ1210 RA26MZ1300 P35201200 P35201100 P35201000 P35200900 P35200800 P35200700 P35200400 P35200200 P35200600 P35200500 P35200300 J310409 Code ΩTY ယ N Ring Plate Handle Support Arbor Rack Plate Plate Plate Axial track device Support Bearing SF-2815 Micro switch TZ-7311 Shaft key 6x6x20 Track Support Pinion 34T Denomination FRONT TRACKING SYSTEM 12-Ŋ <u>ත</u> 10 **-** 15 0 9 8 Ó <u>1</u>5 3

RANGER 112





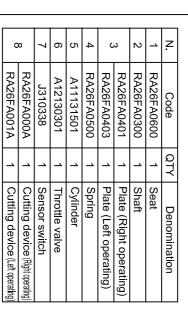
BACK TRACKING SYSTEM

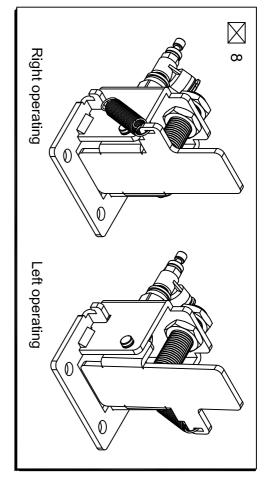
19 8 16 14 15 13 z 12 9 RA26DR064837 RA26DR4700 RA26DR4800 RA26DR4500 RA26DR4601 RA26CH0610 RA26DR4400 RA26DR4300 RA26DR4827 RA26DR4200 RA26DR0310 RA26DR1510 RA26DR1320 RA26DR1310 RA26DR1600 P48200300 P48200300 P48200200 B6000ZZ J2210021 J310339 Code 27 QTY 37 Plate Base Rod Belt Plate Plate Screw Slide carriage Belt plate Pulley 15Z Fixed plate Belt 3.7M L=8368 Belt 2.7M L=6308 Carriage Pulley T=15 Spur gear T=22 Spur gear T=42 Bearing Servo motor 400W Support Sensor Denomination 37#-L 27# RA26DR06437 RA26DR06438 RA26DR4127 Silde Guide $\stackrel{\cdot}{\Rightarrow}$ 13 13 0 4030 4030 3000 QTY **-17** 6 18

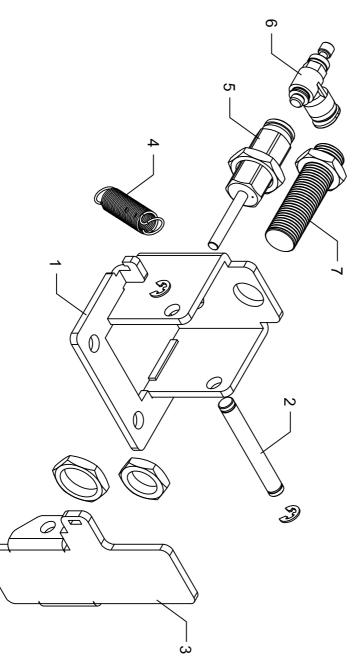
RANGER 112

FEED MOTOR DRIVE

RANGER 112

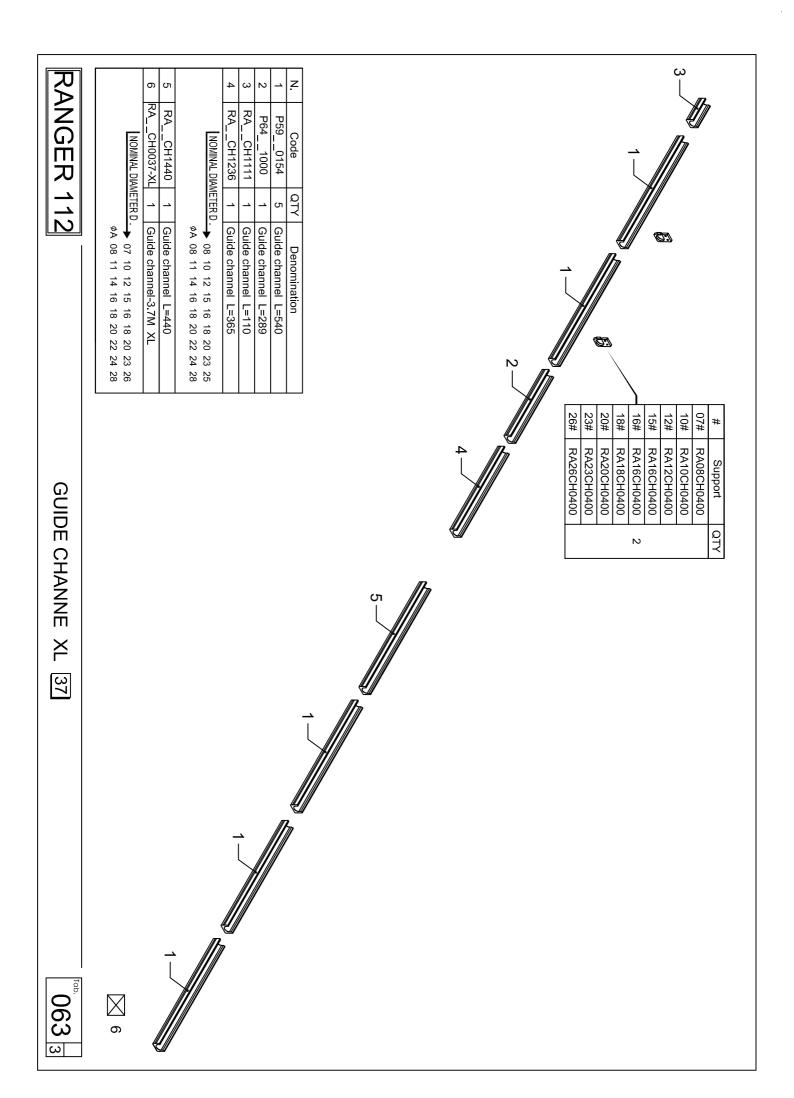


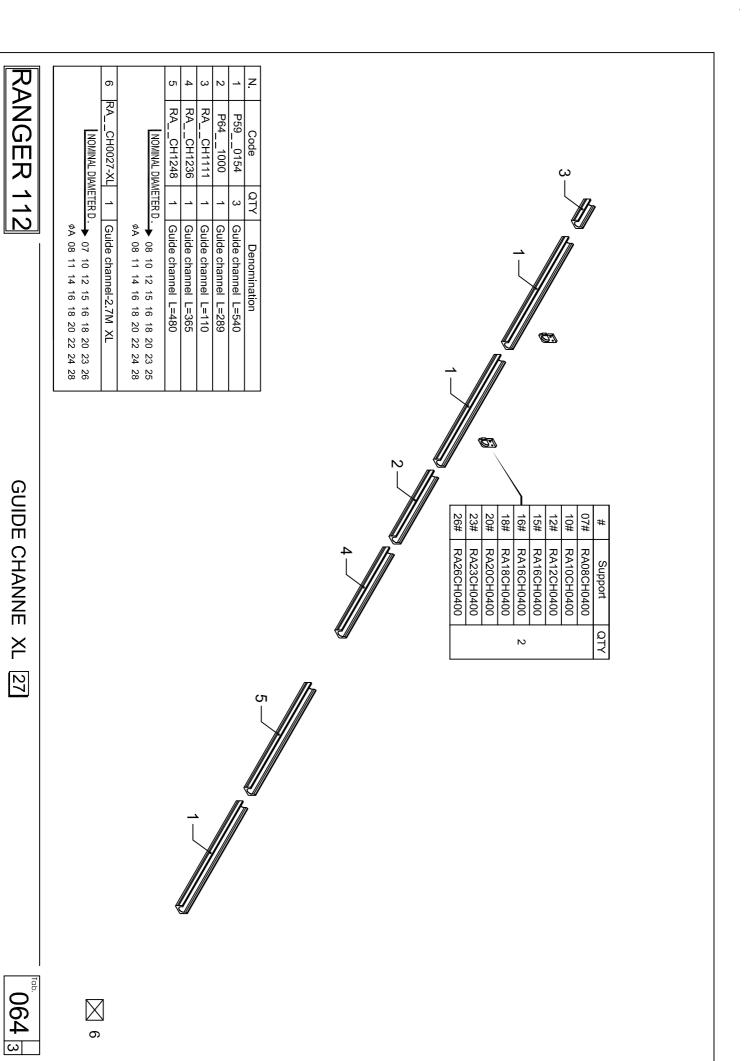




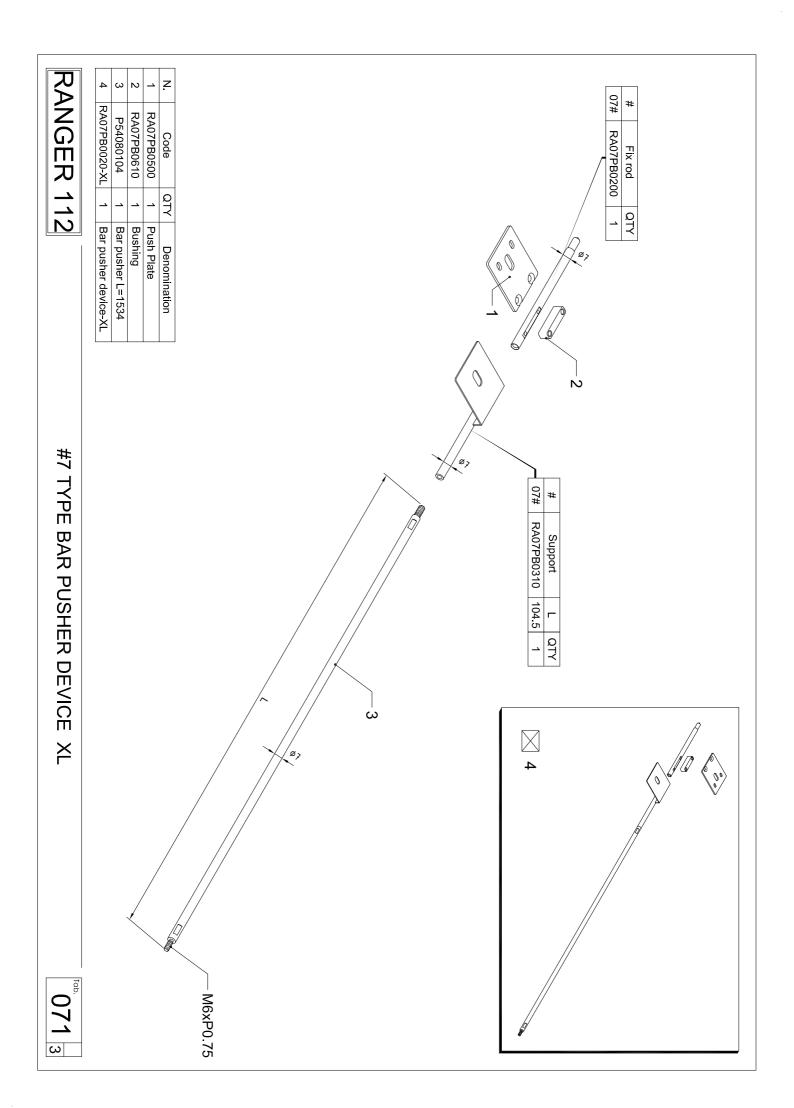
CUTTING DEVICE

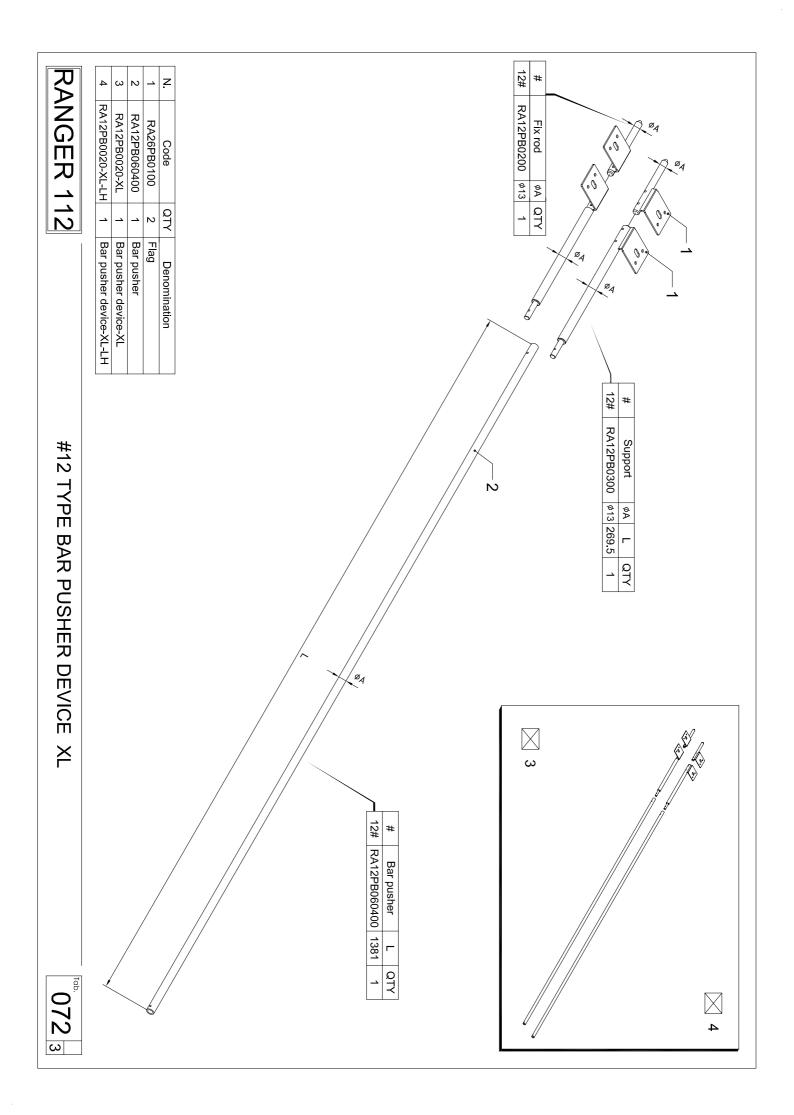
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RANGER 112	J310407	RAZOCIIZUUU	RA26CH0700	RA26CH0500	A12130300	A11131600	RA26CH0300	RA26CH1400	RA26CH1900	RA26CH1600	RA26CH1500	A11133300	RA26CH1800	RA26CH1700	RA26CH0837	RA26CH0827	RA26CH0137	RA26CH0127	Code	
112								1 2	2			ے د	лω		2			_	QTY 27 37	15
	Limit switch		Pusher	Cylinder support	Throttle valve M5-6	Cylinder SDA-12x10-B	Arm	Pusher	Spacer	Support	Cylinder support	Cylinder SDA 20v5	Plate	Seat	Ruubber rod 3.7M L=1200	Ruubber rod 2.7M L=1350	Cover 3.7M L=1175	Cover 2.7M L=1370	Denomination	
COVER																		//		16
/ER										,	/								// «	
				/	//	//	/ /							//		() (7)		R. S.	
060 <u>3</u>				/				[//	//	′		©	<i>B</i> .						₽





RANGER 1	N. Code 1 RA26PB0100 2 RA10PB0200 3 RA10PB0310 4 RA10PB0320 5 RA10PB060400 6 RA10PB0020-XL-LH	S . S . S . S . S . S . S . S . S . S .
		X0 //
2		
	Denomination Flag Fix rod Support-XL L=269.5 Support-XL-LH L=2 Bar pusher L=1386 Bar pusher device-) Bar pusher device-)	Ø ₁₀ 1
	Denomination Flag Fix rod Support-XL L=269.5 Support-XL-LH L=269.5 Support-XL-LH L=1386 Bar pusher device-XL-LH Bar pusher device-XL-LH Bar pusher device-XL-LH	4
+4		
#10 TYPE BAR PU		
YPE E	-5	
BAR F		
IHSU		
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SHER DEVICE		
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070 3		\boxtimes





14 = 8 17 3 12 10 16 15 z 9 ∞ 6 5 4 ယ 2 NOMINAL DIAMETER D. → 02 08 10 12 14 16 18 20 22 24 26 28 Ø 03 09 11 13 15 17 19 21 23 25 27 29 P852010__ P852010__A HP8127001A HP8127002A G55120900 A12130300 HP8127000F P85200800 P85201360 A11130100 P85200600 P85200500 P85200900 P85202300 P85201350 P85200300 P85200200 P85200100 P85200700 Code QTY N N N N N N N 2 2 Anti-vibration device (Right operating) Anti-vibration device (Left operating) Bushing set Arbor Roller Plate Plate Plate Plate Bushing block Indicator plate Flow regulator M5,ø6 Ball BP-06L Anchor Cylinder SDA 25x20 Scale shaft Spacer set Anchor Arbor 16 Denomination 3 12- \boxtimes Right operating 15 2 12 4 5 0 Left operating 6

RANGER 112

MOVEABLE ANTI-VIBRATION DEVICE

081 3

15 14 3 12 1 16 10 z Right operating 9 ∞ 0 Ŋ ZS160425C RA26DR001B RA26DR002B RA26MA2600 RA26DR1910 RA26DR5000 RA26DR5500 RA26DR5300 RA26DR5200 RA26DR2000 RA26DR1010 RA26DR5100 RA26DR1200 607460402 B6002ZZ B6000ZZ P49203100 P49201700 16 Code QTY ω N Bearing 6002ZZ Bearing 6000ZZ Bushing Plate (L) Bushing Shaft Plate Plate Pulley Fixing ring Sychronization (Left operating) Sychronization (Right operating) Hexangular screw Plate (R) Clutch Connector rod Bearing seat Pulley L 17T Denomination Left operating 10 12 ú 15 14 6 5 ∞ O 3

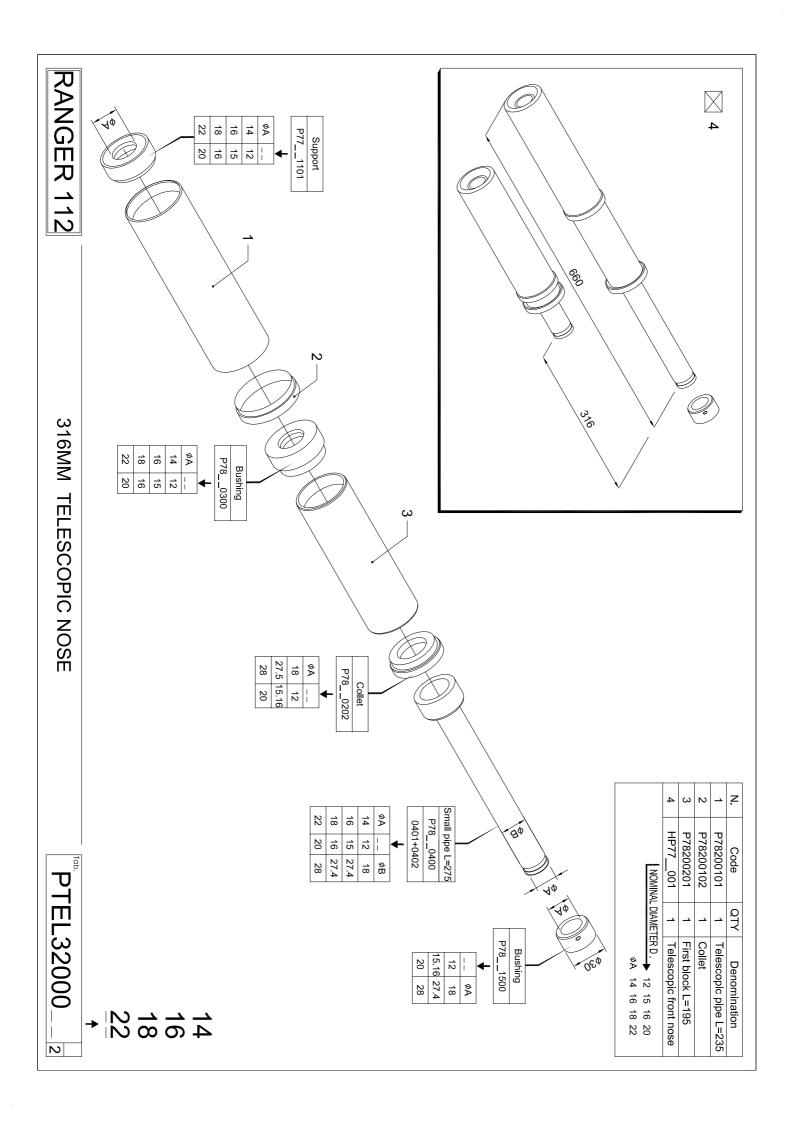
RANGER 112

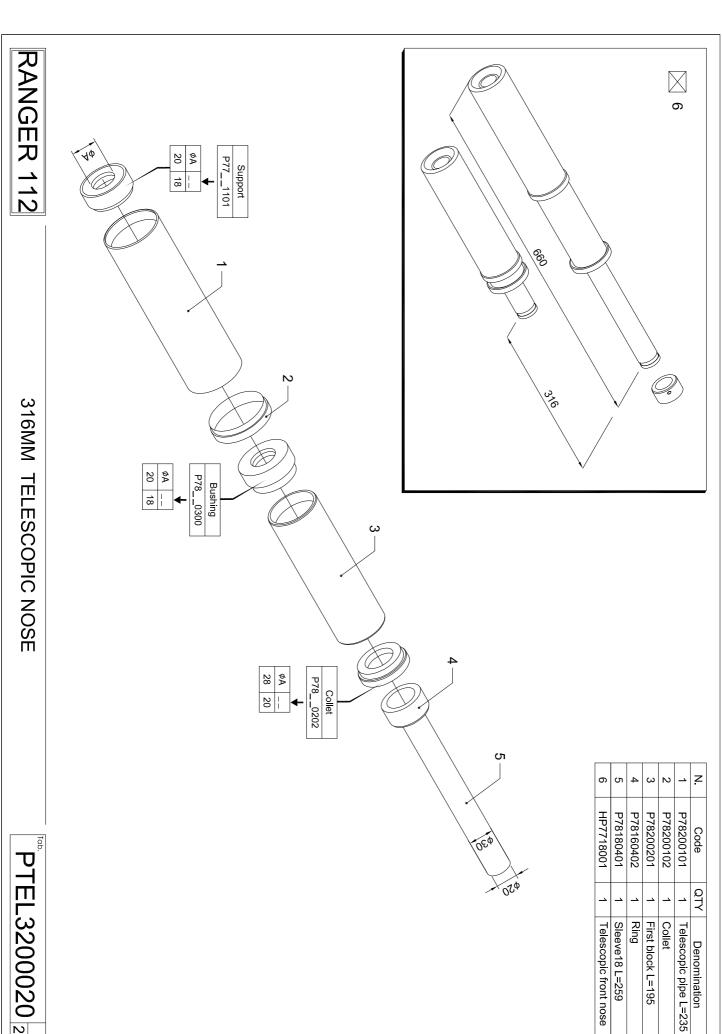
SYCHRONIZATION DEVICE (BELT)

090 2

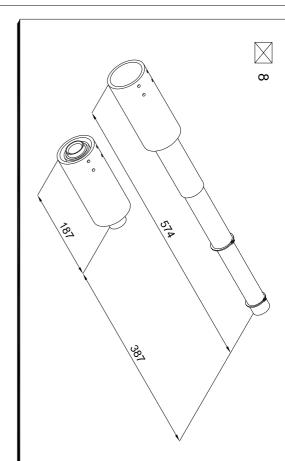
RANGER 112 5 ω N z P77081101 Support P78200201 P78161500 HP7708001 P78200102 P78200101 Code 08 φA ΩTY First block L=195
Bushing Collet Telescopic front nose Telescopic pipe L=235 Denomination 2 P78080300 Bushing 316MM TELESCOPIC NOSE 08 Å P78160202 Collet 5 27.5 φA Small pipe L=275 P78080400 Small pipe L=365 øA PTEL3200008 2 P78080436

RANGER 112 ω N z P77101101 Support P78200201 P78101500 Code P78200101 HP7710001 P78200102 φA 1 ΩTY First block L=195
Bushing Collet Telescopic front nose Telescopic pipe L=235 Denomination N P78100300 Bushing 316MM TELESCOPIC NOSE 1 %A P78100202 Collet ØΑ 15 Small pipe L=275 P78100420 0421+0402 PTEL3200010 2

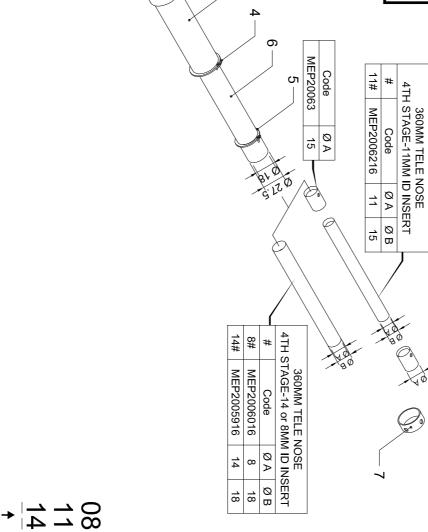




PTEL3200020 2



	8	7	6	5	4	3	2		z
NOMINAL	PTEL32021	P78161500	MEP2005817	ZS07S027	ZS07S035	MEP20055	MEP20053	MEP20061	Code
	_	_	_	_	_	1	_	_	ΩΤΥ
NOMINAL DIAMETER D. ▶ 8 11 14	360MM TELE NOSE-MINUTEMAN-TSUGAMI SS20	BUSHING	360MM TELE NOSE 4TH STAGE TUBE	C RING-S27 (SHAFT)	C RING-S35 (SHAFT)	360MM TELE NOSE 3RD STAGE TUBE	360MM TELE NOSE 2ND STAGE TUBE	360MM TELE NOSE 1ST STAGE TUBE	Denomination



400MM TELE NOSE L=574mm

PTEL32021

